

Model GK291D04

Modally Tuned® Impact Hammer kit, 0 to 1k lbf, 5 mV/lbf, Contents included... (1) 086C04, (1) 352C68, (1) 352B10, (2) 480E09, (2) 003D03, (2) 003C10, (1) 003D10, (1) 070A02, (1) 001A11, Outline 5051

Installation and Operating Manual

This manual contains the 003C10, 003D03, 003D10, 086C04, 352B10, 352C68, 480E09 installation and operating manuals that comprise a Model GK291D04 Modally Tuned® Impact Hammer kit, 0 to 1k lbf, 5 mV/lbf, Contents included... (1) 086C04, (1) 352C68, (1) 352B10, (2) 480E09, (2) 003D03, (2) 003C10, (1) 003D10, (1) 070A02, (1) 001A11, Outline 5051 kit.

For assistance with the operation of this product, contact the PCB Piezotronics, Inc.

Toll-free: 716-684-0001 24-hour SensorLine: 716-684-0001 Fax: 716-684-0987 E-mail: info@pcb.com Web: www.pcb.com







Repair and Maintenance

PCB guarantees Total Customer Satisfaction through its "Lifetime Warranty Plus" on all Platinum Stock Products sold by PCB and through its limited warranties on all other PCB Stock, Standard and Special products. Due to the sophisticated nature of our sensors and associated instrumentation, field servicing and repair is not recommended and, if attempted, will void the factory warranty.

Beyond routine calibration and battery replacements where applicable, our products require no user maintenance. Clean electrical connectors, housings, and mounting surfaces with solutions and techniques that will not harm the material of construction. Observe caution when using liquids near devices that are not hermetically sealed. Such devices should only be wiped with a dampened cloth—never saturated or submerged.

In the event that equipment becomes damaged or ceases to operate, our Application Engineers are here to support your troubleshooting efforts 24 hours a day, 7 days a week. Call or email with model and serial number as well as a brief description of the problem.

Calibration

Routine calibration of sensors and associated instrumentation is necessary to maintain measurement accuracy. We recommend calibrating on an annual basis, after exposure to any extreme environmental influence, or prior to any critical test.

PCB Piezotronics is an ISO-9001 certified company whose calibration services are accredited by A2LA to ISO/IEC 17025, with full traceability to SI through N.I.S.T. In addition to our standard calibration services, we also offer specialized tests, including: sensitivity at elevated or cryogenic temperatures, phase response, extended high or low frequency response, extended range, leak testing, hydrostatic pressure testing, and others. For more information, contact your local PCB Piezotronics distributor, sales representative, or factory customer service representative.

Returning Equipment

If factory repair is required, our representatives will provide you with a Return Material Authorization (RMA) number, which we use to reference any information you have already provided and expedite the repair process. This number should be clearly marked on the outside of all returned package(s) and on any packing list(s) accompanying the shipment.

Contact Information

PCB Piezotronics, Inc. 3425 Walden Ave. Depew, NY14043 USA Toll-free: (800) 828-8840 24-hour SensorLine: (716) 684-0001 General inquiries: <u>info@pcb.com</u> Repair inquiries: <u>rma@pcb.com</u>

For a complete list of distributors, global offices and sales representatives, visit our website, <u>www.pcb.com</u>.

Safety Considerations

This product is intended for use by qualified personnel who recognize shock hazards and are familiar with the precautions required to avoid injury. While our equipment is designed with user safety in mind, the protection provided by the equipment may be impaired if equipment is used in a manner not specified by this manual.

Discontinue use and contact our 24-Hour Sensorline if:

- Assistance is needed to safely operate equipment
- Damage is visible or suspected
- Equipment fails or malfunctions

For complete equipment ratings, refer to the enclosed specification sheet for your product.

Definition of Terms and Symbols

The following symbols may be used in this manual:



DANGER

Indicates an immediate hazardous situation, which, if not avoided, may result in death or serious injury.



CAUTION

Refers to hazards that could damage the instrument.



NOTE

Indicates tips, recommendations and important information. The notes simplify processes and contain additional information on particular operating steps.

The following symbols may be found on the equipment described in this manual:



This symbol on the unit indicates that high voltage may be present. Use standard safety precautions to avoid personal contact with this voltage.



This symbol on the unit indicates that the user should refer to the operating instructions located in the manual.



This symbol indicates safety, earth ground.



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部件名称	铅 (Pb)	汞 (Hg)	镉 (Cd)	六价铬 (Cr(VI))	多溴 联苯 (PBB)	多溴二苯 醚 (PBDE)	
住房	0	0	0	0	0	0	
PCB板	Х	0	0	0	0	0	
电气连接 器	0	0	0	0	0	0	
压电晶 体	Х	0	0	0	0	0	
环氧	0	0	0	0	0	0	
铁氟龙	0	0	0	0	0	0	
电子	0	0	0	0	0	0	
厚膜基板	0	0	Х	0	0	0	
电线	0	0	0	0	0	0	
电缆	х	0	0	0	0	0	
塑料	0	0	0	0	0	0	
焊接	Х	0	0	0	0	0	
铜合金 /黄 铜	Х	0	0	0	0	0	
本表格依据 SJ/T 11364 的规定编制。							
O:表示该有害物质在该部件所有均质材料中的含量均在 GB/T 26572 规定的限量要求以下。							
X:表示该有害物质至少在该部件的某一均质材料中的含量超出 GB/T 26572 规定的限量要求。							
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Hazardous Substances							
Lead (Pb)	Mercury (Hg)	Cadmium (Cd)	Chromium VI Compounds (Cr(VI))	Polybrominated Biphenyls (PBB)	Polybrominated Diphenyl Ethers (PBDE)		
0	0	0	0	0	0		
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Lead is present due to allowed exemption in Annex III or Annex IV of the European RoHS Directive 2011/65/EU.



Model 086C04

Modally Tuned® Impulse Hammer w/force sensor and tips, 0 to 1k lbf, 5 mV/lbf (1.1 mV/N)

Installation and Operating Manual

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电线	0	0	0	0	0	0	
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Installation and Operating Manual ICP[®] Modal / Impulse Force Hammer

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1.0 INTRODUCTION

The ICP[®] Modal / Impulse Force Hammer adapts your FFT analyzer for structural behavior testing. Impulse testing of the dynamic behavior of mechanical structures involves striking the test object with the force-instrumented hammer, and measuring either the resultant motion with an accelerometer or the acoustic signature with a microphone. Structures generally respond as (1) rigid or elastic bodies, (2) finite elements, lumped constant models and (3) distributed parameter models conducting stress-strain (sound) waves.

Testing the functional transfer and transactional characteristics of a mechanical structure involves mounting the accelerometer at one location of interest and striking the test object with the hammer. Modal analysis and modeling involves fixing the accelerometer(s) at one location, impacting the structure at one point and then moving the accelerometer(s) to other points of interest. Integration of the acceleration signal yields velocity compliance, impedance and mobility. The hammer impulse consists of a nearly-constant force over a broad frequency range, and is therefore capable of exciting all resonances in that range. The hammer, size, length, material and velocity at impact determine the amplitude and frequency content (wave shape) of the force impulse. The impact cap material generally determines energy content. The force spectrums of an impact on a stiff steel mass for hammers with their available tips are shown below.

PCB[®] impulse hammers are available in sizes ranging from the mini-impulse hammer to the 12 lb sledgehammer. All sensors in this system are classified as ICP[®] (Integrated Circuit Piezoelectric), low impedance, voltage-mode sensors. Microelectronic, built-in amplifiers standardize sensitivities within a few percent of nominal value, which is adequate for most dynamic applications.

-5 0 Hard Tip (20 lbf pk) -5 Vinyl Cover æ (1.3 lbf pk) -10 -15 -20 100 1000 10000 100000 Frequency (Hz)









086C02, C03, C04, C40 Family Impulse Hammer Response Curves





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-15

-20 + 100

086D20, C41 Family Impulse Hammer Response Curves



1000

Frequency (Hz)

10000



Hammer model selection involves determining the size and mass of the hammer structure which will provide the force amplitude and frequency content required for proper excitation of the structure under test. Large, heavy structures like locomotive frames, tanks and bridges require an instrumented sledgehammer; small structures like compressor blades often require mini-hammers. Some very large structures may require a massive mechanical ram instrumented with a force-sensing impact head.

2.0 **DESCRIPTION**

These hammer consists of an integral, $ICP^{\mathbb{R}}$ quartz force sensor mounted on the striking end of the hammer head. The sensing element functions to transfer impact force into electrical signal for display and analysis. It is structured with rigid quartz crystals and a built-in, micro-electronic, unity gain amplifier. The cable is connected to the end of the handle for convenience, and to avoid connector damage in the event of a "miss hit."

The ICP[®] sensor operates over a standard two-wire cable from a PCB[®] power unit. For reasons of safety, the easily-repairable ribbon wire cable is intended to be the weak link in larger hammer design. The ICP[®] signal conditioner supplies constant current excitation to the sensor over the signal lead and AC couples the output signal. Many FFT analyzers and data acquisition systems have ICP[®] power supply built in.

The hammer is a single, integral unit. Laser-welded construction of the sensor element insures reliable operation in adverse environments. The mechanical assembly is locked together with a structural epoxy adhesive, so it should not be taken apart except at the factory.

The striking end of the hammer has a threaded hole for installation of a variety of impact tips. The tip functions to transfer the force of impact to the sensor and protects the sensor face from damage. Tips of different stiffness allow you to vary the pulse width and frequency content of the force. The specific frequency range can be found in the datasheet supplied with hammer. An extender mass, supplied with most hammers, allows further tuning by concentrating more energy at lower frequencies.

3.0 INSTALLATION AND OPERATION

The hammer is assembled and locked together with structural adhesive at the factory. The tips and extender mass install at opposite ends of the hammer via 10-32 threaded studs. In the case of the model 086E80 mini impulse hammer, the handle is removable.

- 1. With the applicable cables, connect the hammer to an ICP[®] signal conditioner, and then connect that to your analyzer, as shown in the applicable signal conditioners' manual.
- 2. Tighten the cable connectors securely by hand to insure a good electrical contact.
- 3. Switch the power on, and wait a minute or two for the sensor amplifier to turn on and for the coupling capacitor to fully charge. Check the power unit's meter for normal operation (e.g. meter pointer pointing in green area).
- 4. If a meter's pointer points in the red area, look for shorted cables or connections. If a meter's pointer points in the yellow area, look for open cables or connections.
- 5. Connect the accelerometer(s) in a similar manner; referring to the appropriate operating guides for the accelerometer(s) and power unit. When all power unit meters indicate normal operation (green), proceed with the tests following all sensor, power unit and analyzer operating instructions.

4.0 TESTING

Generally speaking, the impact tips affect the hammer impulse frequency content, and the extender affects the signal energy level. Frequency content and energy level are interrelated, so both will be affected by different hammer structures. Hammer velocity at impact will also affect both. In general, massive structures with lower stiffness require the use of the extender and soft impact tip to adequately excite low frequency resonances.

The frequency range of the hammer can be varied by changing the type of tip used. The following guidelines can be used to determine the ideal hammer configuration for a particular test setup:

- 1. For a higher frequency response, use a stiffer tip without the extender mass.
- 2. For a lower frequency response, use a softer tip and install the extender mass.
- 3. To increase motion signal energy, increase the impact velocity and/or hammer mass.

When using the model 086E80 mini impact hammer, the model 084A17 handle is designed for use in frequency ranges lower than those reached when using the model 084A14 handle. When using the model 084A17 handle, best results are achieved by mounting the model 084A13 extender mass to the back of the hammer as shown on the outline drawing. This will improve the low frequency content of the force input to the structure, as well as improve the "feel" of the hammer by offsetting any effective mass added to the handle base by an attached cable.

To test the behavior of your structure and to tailor the frequency bandwidth of the force, follow the following procedure:

1. Strike the test object with the hammer and process the results. Always take several averages to reduce the effects of spurious noise.

CAUTION: Never impact without a hammer tip properly installed on the sensor element. In the case of the model 086E80 mini impact hammer, the sensor element is pre-installed with a steel tip.

- 2. Check the measured results for signal quality (adequate signal-to-noise), no overloads (overload lights or sharp flattening of time history peaks) and no double impacts.
- 3. Analyze results for frequency content, and check to ensure that the reasonably flat portion of the force spectrum is sufficient to cover the structural resonances present in the acceleration spectrum. Often signal energy is sufficient to excite structural resonances at 20 dB below initial low frequency force levels.

During testing, occasionally check and tighten the electrical and mechanical connections. Repeated impacting tends to loosen them, which may result in erratic and noisy signals.

Although modal tuning has done much to eliminate this possibility, bouncing (multiple impacts) or penetration may still occur when using too heavy a hammer on too light a structure or section of a structure. This will appear as an oscillatory component superimposed on the spectrum in your data. Reject such data. Some skill and practice may still be required when testing lighter structures.

PCB's ICP[®] power units providing greater than 10 volts positive signal range (three x 9 volt batteries) prevent undetected overloads in the power unit. Distortion, undershoot and oscillation of the impulse time history, as viewed on the analyzer display, is caused by ringing of the analyzer's anti-aliasing

filters, which is their normal behavior. To view the correct impulse waveform, switch the analyzer to a high-frequency range.

When configuring your oscilloscope or data acquisition system, it is recommended that the input be set to DC coupled. This is because, in some cases, the time constant associated with the equipment's AC coupling circuit is less then that of the impulse hammer and PCB ICP[®] power units. This will cause a small offset in the output voltage of the hammer after impact, which will appear as a negative dip in the response on the down slope of the response with a gradual rise back to zero over a period of time.

5.0 CALIBRATION

Calibration involves testing the functional transfer behavior (sensitivity) of the sensor structure in controlled transactions and environments.

Different hammer structures have different sensitivities. This is because the test structure experiences a force greater than the crystal-sensing elements. The force of impact on the test structure is a function of the total mass of the hammer, while the force on the crystals is a function of only the mass behind them (the impact tip is in front of the crystal-sensing element). Their differences, which depend on the ratio of the tip mass to the head mass, is automatically compensated for when the hammer is properly calibrated, since the extender mass is behind the sensing element. When used, it results in a slight increase in voltage sensitivity (as shown on calibration certificate). Each hammer structure can be easily calibrated to ensure the most accurate data.

A hammer can be calibrated by hitting a freely-suspended mass instrumented with a reference accelerometer. According to Newton's second law of motion, at any instant in time, the force experienced by the mass is simply the mass multiplied by the measured acceleration. On a storage oscilloscope, dividing the peak output signal of the hammer (mV) by the mass (lb or kg), times the peak acceleration (g), gives the hammer sensitivity directly in mV/lb or mV/kg.

Calibration on a FFT analyzer produces the same result as a function of frequency. Since the transfer function of a mass behaving as a rigid body is a consistent (1/M) ratio, the force and the acceleration signals produces a calibration constant (ideally 1/M) for each discrete frequency. The effects of a non-modally tuned hammer will be readily apparent when performing this calibration.

The mass, pendulously suspended or placed on a piece of foam rubber, will behave as a rigid body. Hitting such an instrumented mass is also a good way of checking the normal operation of the hammer and instruments prior to testing. This procedure builds confidence in data results.

6.0 MAINTENANCE

The sealed construction of the sensing element and the bonded construction of the hammer preclude field maintenance. Should service be required, first replace the cables (cables are often the source of trouble) and test operation again. If necessary, return the unit to the factory with a note describing the problem.

7.0 PRECAUTIONS

Although hammers are very rugged in construction, damage can result from misuse. When observed, the following precautions can ensure long life and accurate data.

- 1. Do not attempt to dismantle sensor element from hammer structure. All service should be performed at the factory.
- 2. Never generate more than 5 times the rated impact force range with any hammer. Generally, observe the force rating for five volts output. Excessive impact force may destroy the built-in miniature electronics.
- 3. Never strike an object without an impact tip properly installed in front of the force-sensing element. Damaging the precision-lapped surface of the hammer sensor can affect its behavior.
- 4. During testing, periodically check and tighten tip, extender and cable connections to ensure continued proper operation. Machined flats in the tips and extender facilitate tightening and removal.
- 5. Do not apply voltage to unit without constant current protection.
- 6. Do not apply more than 20 mA of current.
- 7. Do not exceed 30 volts supply voltage.
- 8. Do not subject units to temperatures above 250°F (121°C).
- 9. Ground the analyzer to prevent Electromagnetic Interference (EMI) from fluorescent lights or other sources effecting the signal.

8.0 WARRANTY AND SERVICE

All equipment and repair services provided by PCB Piezotronics, Inc. are covered by a warranty against defective material and workmanship under a **Total Customer Satisfaction** policy. See the supplemental sheet, contained with this manual, for information on our service, repair and return policies, procedures and instructions. When unexpected problems arise, call our 24-Hour SensorLineSM to discuss your immediate dynamic instrumentation needs with a factory representative. PCB guarantees **Total Customer Satisfaction**. If, at any time, for any reason, you are not completely satisfied with any PCB product, PCB will repair, replace, or exchange it at no charge. You may also choose to have your purchase price refunded. Contact PCB for a complete statement of our warranty.

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Website: <u>www.pcb.com</u>	Toll-free (in the US): 800-828-8840

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A2LA ACCREDITED to ISO 17025

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Manual Number: 19198 Manual Revision: B ECO 54793



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Model 480E09

Short sledge Impact Hammer kit, 0 to 5k lbf, 1 mV/lbf, 2.4-lb head, with 2 ea.

Installation and Operating Manual

For assistance with the operation of this product, contact PCB Piezotronics, Inc.

Toll-free: 800-828-8840 24-hour SensorLine: 716-684-0001 Fax: 716-684-0987 E-mail: info@pcb.com Web: www.pcb.com







Repair and Maintenance

PCB guarantees Total Customer Satisfaction through its "Lifetime Warranty Plus" on all Platinum Stock Products sold by PCB and through its limited warranties on all other PCB Stock, Standard and Special products. Due to the sophisticated nature of our sensors and associated instrumentation, field servicing and repair is not recommended and, if attempted, will void the factory warranty.

Beyond routine calibration and battery replacements where applicable, our products require no user maintenance. Clean electrical connectors, housings, and mounting surfaces with solutions and techniques that will not harm the material of construction. Observe caution when using liquids near devices that are not hermetically sealed. Such devices should only be wiped with a dampened cloth—never saturated or submerged.

In the event that equipment becomes damaged or ceases to operate, our Application Engineers are here to support your troubleshooting efforts 24 hours a day, 7 days a week. Call or email with model and serial number as well as a brief description of the problem.

Calibration

Routine calibration of sensors and associated instrumentation is necessary to maintain measurement accuracy. We recommend calibrating on an annual basis, after exposure to any extreme environmental influence, or prior to any critical test.

PCB Piezotronics is an ISO-9001 certified company whose calibration services are accredited by A2LA to ISO/IEC 17025, with full traceability to SI through N.I.S.T. In addition to our standard calibration services, we also offer specialized tests, including: sensitivity at elevated or cryogenic temperatures, phase response, extended high or low frequency response, extended range, leak testing, hydrostatic pressure testing, and others. For more information, contact your local PCB Piezotronics distributor, sales representative, or factory customer service representative.

Returning Equipment

If factory repair is required, our representatives will provide you with a Return Material Authorization (RMA) number, which we use to reference any information you have already provided and expedite the repair process. This number should be clearly marked on the outside of all returned package(s) and on any packing list(s) accompanying the shipment.

Contact Information

PCB Piezotronics, Inc. 3425 Walden Ave. Depew, NY14043 USA Toll-free: (800) 828-8840 24-hour SensorLine: (716) 684-0001 General inquiries: <u>info@pcb.com</u> Repair inquiries: <u>rma@pcb.com</u>

For a complete list of distributors, global offices and sales representatives, visit our website, <u>www.pcb.com</u>.

Safety Considerations

This product is intended for use by qualified personnel who recognize shock hazards and are familiar with the precautions required to avoid injury. While our equipment is designed with user safety in mind, the protection provided by the equipment may be impaired if equipment is used in a manner not specified by this manual.

Discontinue use and contact our 24-Hour Sensorline if:

- Assistance is needed to safely operate equipment
- Damage is visible or suspected
- Equipment fails or malfunctions

For complete equipment ratings, refer to the enclosed specification sheet for your product.

Definition of Terms and Symbols

The following symbols may be used in this manual:



DANGER

Indicates an immediate hazardous situation, which, if not avoided, may result in death or serious injury.



CAUTION

Refers to hazards that could damage the instrument.



NOTE

Indicates tips, recommendations and important information. The notes simplify processes and contain additional information on particular operating steps.

The following symbols may be found on the equipment described in this manual:



This symbol on the unit indicates that high voltage may be present. Use standard safety precautions to avoid personal contact with this voltage.



This symbol on the unit indicates that the user should refer to the operating instructions located in the manual.



This symbol indicates safety, earth ground.



PCB工业监视和测量设备 - 中国RoHS2公布表 PCB Industrial Monitoring and Measuring Equipment - China RoHS 2 Disclosure Table

部件名称	铅 (Pb)	汞 (Hg)	镉 (Cd)	六价铬 (Cr(VI))	多溴 联苯 (PBB)	多溴二苯 醚 (PBDE)	
住房	0	0	0	0	0	0	
PCB板	Х	0	0	0	0	0	
电气连接 器	0	0	0	0	0	0	
压电晶 体	Х	0	0	0	0	0	
环氧	0	0	0	0	0	0	
铁氟龙	0	0	0	0	0	0	
电子	0	0	0	0	0	0	
厚膜基板	0	0	Х	0	0	0	
电线	0	0	0	0	0	0	
电缆	х	0	0	0	0	0	
塑料	0	0	0	0	0	0	
焊接	Х	0	0	0	0	0	
铜合金 /黄 铜	Х	0	0	0	0	0	
本表格依据 SJ/T 11364 的规定编制。							
O:表示该有害物质在该部件所有均质材料中的含量均在 GB/T 26572 规定的限量要求以下。							
X:表示该有害物质至少在该部件的某一均质材料中的含量超出 GB/T 26572 规定的限量要求。							
铅是欧洲RoHS指令2011/65/ EU附件三和附件四目前由于允许的豁免。							

CHINA ROHS COMPLIANCE

Hazardous Substances							
Lead (Pb)	Mercury (Hg)	Cadmium (Cd)	Chromium VI Compounds (Cr(VI))	Polybrominated Biphenyls (PBB)	Polybrominated Diphenyl Ethers (PBDE)		
0	0	0	0	0	0		
Х	0	0	0	0	0		
0	0	0	0	0	0		
Х	0	0	0	0	0		
0	0	0	0	0	0		
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This table is prepared in accordance with the provisions of SJ/T 11364.

O: Indicates that said hazardous substance contained in all of the homogeneous materials for this part is below the limit requirement of GB/T 26572.

X: Indicates that said hazardous substance contained in at least one of the homogeneous materials for this part is above the limit requirement of GB/T 26572.

Lead is present due to allowed exemption in Annex III or Annex IV of the European RoHS Directive 2011/65/EU.



Model 480C02 / 480E09 Battery-Powered ICP[®] Signal Conditioners





Operating Manual with Enclosed Warranty Information

3425 Walden Avenue, Depew, New York 14043-2495

Phone (716) 684-0003

Fax (716) 684-3823

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MANUAL NUMBER: 19175 MANUAL REVISION: B ECO: 52841



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Introduction

Model 480C02 & model 480E09 are rugged, portable, power sources for ICP[®] sensors. These models are nearly identical except model 480C02 is unity gain 1:1 only with no adjustment, while model 480E09 has the additional feature of 3-position gain adjustment (1/10/100). They are powered internally by three replaceable batteries and provide constant current excitation to the charge amplifier within ICP[®] sensors (or to in-line and adaptor style amplifiers) and decouples the sensor output signal from the power. Signal output is a high quality, voltage output compatible with standard readout, recording or acquisition instruments.



Figure 1: Model 480C02 Signal Conditioner





Figure 2: Model 480E09 Signal Conditioner

Description

Models 480C02 / 480E09 contain three, PP3 size, 9 volt batteries connected in series to provide DC power to internal electronics which provide regulation for approximately 2.6 mA of constant current power. Connections include two BNC jacks, one for Sensor (ICP[®] power/input) and one for Scope (output to scope, data recorder, or DAQ). The front panel meter indicates the voltage output when connected to a sensor and is color coded for various fault conditions, shown in Figure 1 & 2. Optional connections include sockets for EXT PWR and BATT CHG. A central, three-position rocker switch allows off, on and momentary battery test functionality.

Model 480E09 has the additional 3-position gain adjustment that multiplies the signal output through the SCOPE connection. It has 2 additional settings beyond the 480C02, 10x and 100x, shown in Figure 2.

PCB PIEZOTRONICS

Operation

Internal electronics include a capacitor and resistor that decouples the sensor output signal from the DC power. With no sensor connected, move power switch to "ON" position. The front panel voltmeter measures the battery voltage with full scale set at 27 volts (+27 volts for new batteries), see Figure 1. When an ICP[®] sensor is connector to the input "XDCR" jack, the meter will indicate approximately mid-scale (+11 volts nominal) if the sensor's internal amplifier and cables are functioning properly without damage. Some sensors use a 5 volt excitation and in this case the meter will read at the lower edge of the green region.



Figure 3: Models 480C02 / 480E09 Signal Conditioner Schematic



If the sensor amplifier and/or cable are damaged to short open, the meter will indicate in the full scale (vellow) area. Should the sensor amplifier and/or cable be damaged to short closed, the meter will indicate zero volts (red area). Immediately after connecting readout instrument, (oscilloscope, meter, recorder, etc.) to the output jack, the 47 µF coupling capacitor will begin charging through the internal resistor and input resistance of the readout instrument. This charging will cause an apparent "drifting" of the output signal until the capacitor is fully charged. Such drifting is considered normal operation.



Coupling Time Constant (TC), AC Coupled

The coupling discharge time constant (DTC) is the product of the capacitor (47 μ F) and the parallel internal resistor and the input resistance of the readout instrument (See Figure 4, Equation 1).

Equation 1:

TC (sec) = C_c (microfarads) x R_{in} (ohms)



Low Frequency Response Table

The small amount of leakage through the 47µF coupling capacitor will typically result in a +30 mV maximum offset with a 1.0 megaohms readout load. Normally, it is desirable to keep the coupling discharge time constant (DTC) long with respect to the sensor discharge time constant to minimize the effect of the coupling distance time constant on low frequency response. Typical coupling discharge time constants for various values of readout input resistance are shown in Table 1.

Figure 4: Diagram: AC Coupling



DC Coupling for Low-Frequency Response

With the 480C02 / 480E09 connected as shown in Figure 5, the low frequency response of the coupling circuit is determined by the relationship in Equation 2. This requires use of a BNC Tee. Figure 6 below provides a comparison of AC vs DC coupling the same signal.



Figure 5: Direct Coupled Mode



Figure 6: Diagram: AC vs DC Coupling

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Performance Limits

Output Voltage Limits

Certain ICP sensors are capable of 10-volt output voltage swing. Models 480C02 / 480E09 with 27 volt supply will allow the positive-going side of the signal to go to +14 volts. The negative signal side is capable of -8 volts assuming a 10 volt turn-on for the sensor. This must be taken into consideration or resulting outputs may show signs of clipping.

Constant Current Limits

When using battery powered signal conditioners, battery life can be a concern. The current output of model 480C02 / 480E09 is fixed at approximately 2.6 mA. This current will adequately handle high-frequency signals in cables up to approximately 100 feet (31 meters) in length. Longer cables can be driven but it sacrifices some high-frequency response. PCB line powered signal conditioners (482 Series / 483 Series) should be considered for cable lengths beyond 100 feet (31 meters) as they provide up to 20 mA of drive current.

Battery Considerations

Battery Test

Models 480C02 / 480E09 incorporate a momentary battery test position in the 3 position switch. When the rocker switch is depressed to the right, the meter switched from the "XDCR" jack to the battery power high-side. Normal circuit operation is not affected by this change and releasing the rocker returns the meter to the transducer fault monitor function. It is recommended to confirm the status of batteries before initiating a test. Replace batteries any time the pointer does not reach the BATT OK position or further when the BATT Test switch is depressed. A slightly low reading will limit the usable output of most sensors but will not cause damage to the model 480C02 or connected sensors.



Battery Life & Replacement

Typical battery life is 100 hours at gain of 1 or 40 hours at gain of 10 or 100 when using high quality alkaline batteries, assuming the unit is turned off when not in use. When a BATT Test fail occurs, find and carefully remove the Philips head screw on the back of model 480C02. The housing will easily separate from the working portion of the unit and expose the batteries. Gently remove each of the battery connectors to avoid damage and remove the batteries. Re-install new PP3, 9-volt batteries in same locations, making sure all are of the same type and same manufacturer. Replace housing and hand-tighten screw on back of unit. It is not recommended to mix type or manufacturer of batteries or damage can occur as batteries rupture or leak. It is recommended to remove batteries from units not in frequent use, to avoid any damage from long-term battery corrosion.

Optional Power Connections

Rechargeable Battery Use & Charging

WARNING, models 480C02 / 480E09 <u>do not</u> ship with rechargeable batteries and PCB external battery chargers are suitable for use with Nickel-Cadmium (Ni-Cad) rechargeable batteries only. It should not be used with alkaline or other non-rechargeable batteries.

Use of battery chargers, model 488A02 (110 VAC) or model F488A02 (220 VAC) should only be attempted after installation of suitable batteries. Plug 488A02 charging connector into front panel jack and with unit off, recharge for 14 hours. Charger supplies 10 mA constant current to the rechargeable batteries in the unit. Batteries should not be charged in areas near combustible materials or left unattended. Disconnect all power if any evidence of overheating occurs.



External Power Connection

The external power connector (which mates with a #750 Switchcraft telephone plug) is intended for use when longer battery life is desired. Insertion of the plug into the jack isolates the battery power connection, powering the unit from only the secondary power source. A variety of battery packs were previously available for use with this connection, one being model 073A05. They are still viable for use, but are no longer in production from PCB.

CAUTION: Insert plug into EXT PWR prior to powering ON the external power supply.

PCB PIEZOTRONICS

Warranty

PCB instrumentation is warranted against defective material and workmanship for 1 year unless otherwise expressly specified. Damage to instruments caused by incorrect power or misapplication, is not covered by warranty. *If there are any questions regarding power, intended application, or general usage, please consult with your local sales contact or distributor.* Batteries and other expendable hardware items are not covered by warranty.

Calibration & Service

Aside from battery replacement, no maintenance is required for this unit. The 480C02 contains no field serviceable parts and is not designed for field repair. Field repair is typically **NOT** recommended and may void any warranty. If factory service is required, return the instrumentation according to the "Return Procedure" stated below. *A repair and/or replacement quotation will be provided prior to servicing at no charge*. Before returning the unit, please consult a factory PCB applications engineer concerning the situation as certain problems can often be corrected with simple on-site procedures.

PCB will perform calibrations on model 480C02 on request. Typical calibration validates the unit functions within factory new parameters, includes replacement of batteries and a factory calibration certificate.

Return Procedure

To expedite returned instrumentation, contact a factory PCB applications engineer for a RETURN MATERIAL AUTHORIZATION (RMA) NUMBER. When requesting the RMA, please be prepared to provide the model number, serial number, a brief written description of the problem, your company details, and any other pertinent information. We also recommend a copy of this information should be provided in the package with the instrument.

Customers outside the U.S. should consult their local PCB distributor for information on returning equipment. For exceptions, please contact the International Sales department at PCB to request shipping instructions and an RMA. For assistance, please call (716) 684-0003, or fax us at (716) 684-3823. You may also receive assistance via e-mail at **info@pcb.com** or visit our web site at **www.pcb.com**.



Total Customer Satisfaction

PCB, a division of PCB Piezotronics, guarantees **Total Customer Satisfaction**. If, at any time, for any reason, you are not completely satisfied with any PCB product, PCB will repair, replace, or exchange it at no charge. You may also choose, within the warranty period, to have your purchase price refunded.

PCB offers to all customers, at no charge, 24-hour phone support. This service makes product or application support available to our customers, day or night, seven days a week. When unforeseen problems or emergency situations arise, call the **PCB Hot Line at (716) 684-0003**, and an application specialist will assist you.



3425 Walden Avenue, Depew, NY 14043-2495 Phone: (716) 684-0003 • USA Fax: (716) 684-3823 • INTL Fax: (716) 684-4703

ICP ® is a registered trademark of PCB Piezotronics, Incorporated, which uniquely identifies PCB sensors that incorporate built-in microelectronics.

MANUAL NUMBER: 19175 MANUAL REVISION: B



Model 352B10

Miniature, lightweight (0.7 gm), ceramic shear ICP® accel., 10 mV/g, 2 to

Installation and Operating Manual

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Х	0	0	0	0	0			
0	0	0	0	0	0			
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General OPERATING GUIDE

for use with

PIEZOELECTRIC ICP[®] ACCELEROMETERS

SPECIFICATION SHEET, INSTALLATION DRAWING AND CALIBRATION INFORMATION ENCLOSED

PCB ASSUMES NO RESPONSIBILITY FOR DAMAGE CAUSED TO THIS PRODUCT AS A RESULT OF PROCEDURES THAT ARE INCONSISTENT WITH THIS OPERATING GUIDE.

1.0 INTRODUCTION

Congratulations on the purchase of a quality, ICP[®] acceleration sensor. In order to ensure the highest level of performance for this product, it is imperative that you properly familiarize yourself with the correct mounting and installation techniques before attempting to operate this device. If, after reading this manual, you have any additional questions concerning this sensor or its application, feel free to call a factory Application Engineer at 716-684-0001 or your nearest PCB sales representative.

2.0 ICP[®] ACCELEROMETERS

Powered by simple, inexpensive, constant-current signal conditioners, these sensors are easy to operate and interface with signal analysis, data acquisition and recording instruments. The following features further characterize ICP^{\circledast} sensors:

- Fixed voltage sensitivity, regardless of cable type or length.
- Low-impedance output signal, which can be transmitted over long cables in harsh environments with virtually no loss in signal quality.
- Two-wire operation with low cost coaxial cable, twoconductor ribbon wire or twisted-pair cabling.
- Low-noise, voltage-output signal compatible with standard readout, signal analysis, recording, and data acquisition equipment.
- Low cost per-channel ICP[®] accelerometers require only an inexpensive, constant-current signal conditioner to operate.

• Intrinsic self-test feature – monitoring the sensor's output bias voltage provides an indication of proper operation, faulty condition, and bad cables.

In the rear of this manual you will find a **Specification Sheet**, which provides the complete performance characteristics of your particular sensor.

3.0 OPTIONAL FEATURES

Many sensors are supplied with standard, optional features. When listed before the model number, the following prefix letters indicate that the sensor is manufactured or supplied with a particular optional feature: "A" option: adhesive mount; "HT" option: extended high temperature range; "J" option: electrically ground isolated; "M" option: metric mounting thread; "Q" option: extended discharge time constant; "T" option: built-in transducer electronic data sheet (TEDS); and "W" option: attached, water-resistant cabling. Other prefix letters, such as "K", "KR", "GK", "GKR", "KL", and "GKL", indicate that the sensor is ordered in kit form, including interconnect cabling and signal conditioner. If you have any questions or concerns regarding optional features, consult the Vibration Division's product catalog or contact a PCB factory representative.

4.0 INSTALLATION OVERVIEW

When choosing a mounting method, consider closely both the advantages and disadvantages of each technique. Characteristics like location, ruggedness, amplitude range, accessibility, temperature, and portability are extremely critical. However, the most important and often overlooked consideration is the effect the mounting technique has on the high-frequency performance of the accelerometer.

[®] ICP is a registered trademark of PCB Group, Inc., which uniquely identifies PCB sensors that incorporate built-in microelectronics.

Shown in figure 1 are six possible mounting techniques and their effects on the performance of a typical piezoelectric accelerometer. (Note that not all of the mounting methods may apply to your particular sensor). The mounting configurations and corresponding graph demonstrate how the high-frequency response of the accelerometer may be compromised as mass is added to the system and/or the mounting stiffness is reduced.

NOTE: The low-frequency response is unaffected by the mounting technique. This roll-off behavior is typically fixed by the sensor's built-in electronics. However, when operating AC-coupled signal conditioners with readout devices having an input impedance of less than one megohm, the low frequency range may be affected. If necessary, contact a factory representative for further assistance.



Figure 1. Assorted Mounting Configurations and Their Effects on High Frequency

4.1 STUD MOUNT

This mounting technique requires smooth, flat contact surfaces for proper operation and is recommended for permanent and/or secure installations. Stud mounting is also recommended when testing at high frequencies.

NOTE: Do NOT attempt mounting on curved, rough, or uneven surfaces, as the potential for misalignment and limited contact surface may significantly reduce the sensor's upper operating frequency range.

STEP 1: First, prepare a smooth, flat mounting surface, then drill and tap a mounting hole in the center of this area as shown in Figure 2 and in accordance with the enclosed **Installation Drawing**.



Figure 2. Mounting Surface Preparation

A precision-machined mounting surface with a minimum finish of 63 μ in (0.00016 mm) is recommended. (If it is not possible to properly prepare the test structure mounting surface, consider adhesive mounting as a possible alternative). Inspect the area, checking that there are no burrs or other foreign particles interfering with the contact surface.

STEP 2: Wipe clean the mounting surface and spread on a light film of grease, oil, or similar coupling fluid prior to installation.



Figure 3. Mounting Surface Lubrication

Adding a coupling fluid improves vibration transmissibility by filling small voids in the mounting surface and increasing the mounting stiffness. For semipermanent mounting, substitute epoxy or another type of adhesive.

STEP 3: Screw the mounting stud into the base of accelerometer and hand-tighten (this step is unnecessary for units having an integral mounting stud). Then, screw the sensor into the tapped hole that was prepared in the test object. Tighten the unit in place by applying, with a torque wrench, the recommended mounting torque, as listed on the enclosed **Installation Drawing**.

NOTE: It is important to use a torque wrench during this step. Under-torquing the sensor may not adequately couple the device; over-torquing may result in stud failure.

4.2 ADHESIVE MOUNT

Adhesive mounting is often used for temporary installation or when the test object surface cannot be adequately prepared for stud mounting. Adhesives like hot glue and wax perform well for temporary installations whereas two-part epoxies and quick-bonding gels (super glue) provide a more permanent installation. Two techniques are used for adhesive mounting; they are via an adhesive mounting base (method 1 below) or direct adhesive mounting (method 2 below).

NOTE: Adhesively mounted sensors often exhibit a reduction in high-frequency range. Generally, smooth surfaces and stiff adhesives provide the best high frequency response.

METHOD 1 - Adhesive Mounting Base

This method involves attaching a base to the test structure, then securing the sensor to the base. This allows for easy removal of the accelerometer. Also, since many bases are manufactured of "hard-coated" aluminum, they provide electrical isolation to eliminate ground loops and reduce electrical interference that may propagate from the surface of the test object.

STEP 1: Prepare a smooth, flat mounting surface. A minimum surface finish of 63 μ in (0.00016 mm) generally works best.

STEP 2: Stud-mount the sensor to the flat side of the appropriate adhesive mounting base according to the guidelines set forth in **STEPS 2** and **3** of the Stud Mount Procedure presented above.

STEP 3: Place a small portion of adhesive on the underside of the mounting base (the underside is discernable by the concentric grooves which are designed to accept the adhesive). Firmly press down on the assembly to displace any extra adhesive remaining under the base.



Figure 4. Mounting Base: Adhesive Installation

METHOD 2 - Direct Adhesive Mount

For restrictions of space or for convenience, most sensors can be adhesive-mounted directly to the test structure (an exception being units having integral mounting studs).

STEP 1: Prepare a smooth, flat mounting surface. A minimum surface finish of 63 μ in (0.00016 mm) generally works best.

STEP 2: Place a small portion of adhesive on the underside of the sensor. Firmly press down on the top of the assembly to displace any adhesive. Be aware that

excessive amounts of adhesive can make sensor removal difficult. Also, adhesive that may invade the tapped mounting hole in the base of the sensor will compromise future ability to stud mount the unit.



Figure 5. Direct Adhesive Mounting

4.2-1 ADHESIVE MOUNT REMOVAL (other than wax)

NOTE: A debonder should always be used to avoid sensor damage.

To avoid damaging the accelerometer, a debonding agent must be applied to the adhesive prior to sensor removal. With so many adhesives in use (everything from super glues, dental cement, epoxies, etc), there is no universal debonding agent available. The debonder for the Loctite 454 adhesive that PCB offers is Acetone. If you are using anything other than Loctite 454, you will have to check with the individual manufacturers for their debonding recommendations. The debonding agent must be allowed to penetrate the surface in order to properly react with the adhesive, so it is advisable to wait a few minutes before removing the sensor.

After the debonding agent has set, you can use an ordinary open-end wrench if the accelerometer has a hex base or square base, or the supplied removal tool for teardrop accelerometers. After attaching either, use a gentle shearing (or twisting) motion (by hand only) to remove the sensor from the test structure.

4.3 MAGNETIC MOUNT

Magnetic mounting provides a convenient means for making quick, portable measurements and is commonly used for machinery condition monitoring, predictive maintenance, spot checks, and vibration trending applications.

NOTE: The correct magnet choice and an adequately prepared mounting surface are critical for obtaining reliable measurements, especially at high frequencies. Poor installations can cause as much as a 50% drop in the sensor frequency range.

Not every magnet is suitable for all applications. For example, rare earth magnets are commonly used because

of their high strength. Flat magnets work well on smooth, flat surfaces, while dual-rail magnets are required for curved surfaces such as motor housings and pipes. In the case of non-magnetic or rough surfaces, it is recommended that the user first weld, epoxy, or otherwise adhere a steel mounting pad to the test surface. This provides a smooth location for mounting and a target to insure that subsequent measurements for trending purposes are taken at the same location.



Figure 6. Magnet Types

STEP 1: Prepare a smooth, flat mounting surface. A minimum surface finish of 63 μ in (0.00016 mm) generally works best. After cleaning the surface and checking for burrs, apply a light film of silicone grease, machine oil, or similar-type coupling fluid.

STEP 2: After choosing the correct magnet type, inspect the magnet, verifying that its mounting surfaces are flat and smooth.

STEP 3: Stud-mount the accelerometer to the appropriate magnet according to the guidelines set forth in **STEP 3** of the above Stud Mount Procedure.

STEP 4: To avoid damage to the sensor, install the magnet/sensor assembly to the prepared test surface by gently "rocking" or "sliding" it into place.



Figure 7. Magnet Mounting

CAUTION: Magnetically mounting of an accelerometer has the potential to generate very high (and very damaging) acceleration (g) levels. To prevent such damage, exercise caution and install the assembly gently by rocking it into place. If shock is expected to be a particular concern, use a sensor with built-in shock protection. For further assistance, contact a factory representative.

4.4 HANDHELD OR PROBE TIP MOUNT

This method is NOT recommended for most applications. Both the accuracy and repeatability at low (<5 Hz) and high frequency (>1 kHz) ranges are questionable. It is generally used only for machinery condition monitoring, when installation space is restricted, or other portable trending applications. The technique, however, can be useful for initially determining locations of greatest vibration to establish a permanent sensor installation point.

5.0 CABLING

Care and attention to cable installation and cable condition is essential as the reliability and accuracy of any measurement system is no better than that of its weakest link. Do to the nature of vibration measurements, all sensor cables will ultimately fatigue and fail. Good installation practice will extend the life of a cable, however, it is highly recommended to keep spare cables on hand to enable continuation of the test in the event of a cable failure.

STEP 1: Ascertain that you have the correct cable type.

One cable type cannot satisfy all applications. ICP® sensors can be operated with any ordinary two-wire or coaxial cable. Special, low-noise cables that are typically recommended for use with high-impedance, charge-output sensors can also be used. For applications requiring conformity to $\mathbf{C}\mathbf{\epsilon}$, low noise cables are essential. Industrial applications often require shielded, twisted-pair cables to reduce the effects of EMI and RFI that is present near electrical motors and machinery. Teflon-jacketed cabling may be necessary to withstand corrosive environments and higher temperatures. Consult the Vibration Division's product catalog for more information about cables or feel free to contact a factory representative for a specific recommendation on cables that are best suited for your application.

STEP 2: Connect the cable to the accelerometer.

A small amount of thread-locking compound placed on the connector threads prior to attachment helps secure the cable during testing. In wet, oily, or dirty environments, the connection can be sealed with silicone rubber sealant, O-rings, and flexible, heat-shrink tubing.

Coaxial Cables: Make connection by inserting the cable's connector pin into the sensor's mating socket. Then thread the connector into place by turning the cable connector's outer shell onto the accelerometer's electrical connector.

NOTE: Do not spin the accelerometer while holding the cable connector stationary, as this will cause undue

friction on the center pin of the cable connector and lead to premature fatigue.

Multi-pin connectors: Make connection by inserting the sensor's mating pins onto the cable connector's mating sockets. Then thread the connector into place by turning the cable connector's outer shell onto the accelerometer's electrical connector.

Pigtail Connections: Certain miniature accelerometers and shock sensors are provided with lightweight cables attached to "Pigtail" connections. This type of connection reduces overall weight and incidence of connection intermittency under shock conditions. In the event of a cable or connection failure, the cables may be repaired in the field simply by re-soldering the stripped leads to the exposed pins on the sensor. (Check the **Installation Drawing** to determine signal and ground pins). In many cases, it is also helpful to protect the solder joint with heat-shrink tubing or epoxy.

NOTE: If you do not have the experience or resources to attach pigtail leads, consult PCB to discuss factory attachment. Damage to internal electronics may be caused by excessive heat during soldering and such failure is not covered by warranty.

STEP 3: Route the cable to the signal conditioner, making certain to relieve stress on the sensor/cable connection. Also, minimize cable motion by securing it with tape, clamps or ties at regular intervals.

Common sense should be used to avoid physical damage and minimize electrical noise. For instance, avoid routing cables near high-voltage wires. Do not route cables along floors or walkways where they may be stepped on or become contaminated. To avoid ground loops, shielded cables should have the shield grounded at one end only, typically at the signal conditioner.

STEP 4: Finally, connect the remaining cable end to the signal conditioner. It is good practice to dissipate any electrical charge that may have accumulated in the cable by shorting the signal pin to the ground pin or shell prior to attachment.

6.0 POWERING

All ICP^{\circledast} sensors require constant current excitation for proper operation. For this reason, use only PCB constantcurrent signal conditioners or other approved constantcurrent sources. A typical system schematic is shown in Figure 8.

NOTE: Damage to the built-in electronics resulting from the application of incorrect power, or the use of an unapproved power source, is NOT covered by warranty.



Figure 8. Typical System Schematic

The power supply consists of a current-regulated, 18 to 30 VDC source. This power is regulated by a current-limiting circuit, which provides the constant-current excitation required for proper operation of ICP[®] sensors. In general, battery-powered devices offer versatility for portable, low-noise measurements, whereas line-powered units provide the capability for continuous monitoring. Consult the Vibration Division's product catalog for more information about signal conditioners.

NOTE: Under no circumstances should a voltage be supplied to an ICP[®] accelerometer without a current-regulating diode or equivalent electrical circuit. This may include ohmmeters, multi-meters and continuity testers.

Meters or LEDs are used on PCB signal conditioners to monitor the bias voltage on the sensor output signal, to check sensor operation, and detect cable faults. Normally, a "yellow" reading indicates an open circuit; "green" indicates normal operation; and "red" indicates either a short or overload condition. Finally, a capacitor at the output stage of the device removes the sensor output bias voltage from the measurement signal. This provides a zero-based, AC-coupled output signal that is compatible with most standard readout devices.

NOTE: Units having a low bias voltage may be in the "red," when actually they are working properly. If suspect, the bias voltage can be checked with a voltmeter attached to a "T" connector installed on the input connector to the signal conditioner.

Note: For readout devices having an input impedance near one gigohm (as encountered with some A to D converters), it may be necessary to place a one megohm resistor in parallel to the readout input to eliminate slow turn-on and signal drift.

Today, many FFT analyzers, data acquisition modules, and data collectors have the proper constant-current excitation built-in for direct use with ICP[®] sensors. Before using this feature, however, check that the supply voltage and constant current are within acceptable limits for use with your particular sensor. (Check enclosed **Specification Sheet**). Please contact the respective signal conditioner manufacturer or check the product manual for more information.

7.0 OPERATING

After completing the system setup, switch on the signal conditioner and allow 1 to 2 minutes for the system to stabilize. The meter (or LED) on the signal conditioner should be reading "green." This indicates proper operation and you may begin taking measurements. If a faulty condition is indicated (red or yellow reading), first check all system connections, then check the functionality of the cable and signal conditioner. If the system still does not operate properly, consult a PCB factory representative.

NOTE: Always operate the accelerometer within the limitations listed on the enclosed **Specification Sheet**. Operating the device outside these parameters can cause temporary or permanent damage to the sensor.

8.0 ACCELEROMETER CALIBRATION

Accelerometer calibration provides, with a definable degree of accuracy, the necessary link between the physical quantity being measured and the electrical signal generated by the sensor. In addition, other useful information concerning operational limits, physical parameters, electrical characteristics, or environmental influences may also be determined. Without this link, analyzing data becomes a nearly impossible task. Fortunately, most sensor manufacturers provide a calibration record that documents the exact characteristics of each sensor. (The type and amount of data varies depending on the manufacturer, sensor type, contractual regulations, and other special requirements).

Under normal conditions, piezoelectric sensors are extremely stable, and their calibrated performance characteristics do not change over time. However, the sensor may be temporarily or permanently affected by harsh environments influences or other unusual conditions that may cause the sensor to experience dynamic phenomena outside of its specified operating range. This change manifests itself in a variety of ways, including: a shift of the sensor resonance due to a cracked crystal; a temporary loss of low-frequency measuring capability due to a drop in insulation resistance; or total failure of the built-in microelectronic circuit due to a high mechanical shock.

For these reasons, it is recommended that a recalibration cycle be established for each accelerometer. This schedule is unique and is based on a variety of factors, such as: extent of use, environmental conditions, accuracy requirements, trend information obtained from previous calibration records, contractual regulations, frequency of "crosschecking" against other equipment, manufacturer recommendation, and any risk associated with incorrect readings. International standards, such as ISO 10012-1, provide insight and suggest methods for determining recalibration intervals for most measuring equipment. With the above information in mind and under "normal" circumstances, PCB conservatively suggests a 12- to 24-month recalibration cycle for most piezoelectric accelerometers.

NOTE: It is good measurement practice to verify the performance of each accelerometer with a Handheld Shaker or other calibration device before and after each measurement. The PCB Handheld Shaker operates at a fixed frequency and known amplitude (1.0 g) to provide a quick check of sensor sensitivity.

8.1 RECALIBRATION SERVICE

PCB offers recalibration services for our piezoelectric accelerometers, as well as units produced by other manufacturers. Our internal metrology laboratory is certified to ISO 9001, accredited by A2LA to ANSI/IEC 17025 and ANSI/NCSL Z540-1, complies with ISO 10012-1 (and former MIL-STD-45662A), and uses equipment directly traceable to NIST. Our investment in equipment, traceability and conformance to industry standards ensures accurate calibration against relevant specifications, in a timely fashion.

8.2 BACK-TO-BACK CALIBRATION THEORY

Many companies choose to purchase the equipment necessary to perform the recalibration procedure in house. While this may result in both a savings of time and money, it has also been attributed to incorrect readings and costly errors. Therefore, in an effort to prevent the common mistakes associated with customer-performed calibration, this document includes a broad overview of the Back-to-Back Calibration technique. This technique provides a quick and easy method for determining the sensitivity of a test accelerometer over a wide frequency range.

Back-to-Back Calibration is perhaps the most common method for determining the sensitivity of piezoelectric accelerometers. This method relies on a simple comparison to a previously calibrated accelerometer, typically referred to as a reference standard.



Figure 9. Reference Standard Accelerometer

These high-accuracy devices, which are directly traceable to a recognized standards laboratory, are designed for stability, as well as configured to accept a test accelerometer. By mounting a test accelerometer to the reference standard and then connecting this combination to a suitable vibration source, it is possible to vibrate both devices and compare the data as shown in Figure 10. (Test set-ups may be automated and vary, depending on the type and number of accelerometers being calibrated).



Figure 10. Typical Back-to-Back Calibration System

Because the acceleration is the same on both sensors, the ratio of their outputs (V_T/V_R) must also be the ratio of their sensitivities. With the sensitivity of the reference standard (S_R) known, the exact sensitivity of the test sensor (S_T) is easily calculated by using the following equation:

$$S_T = S_R (V_T / V_R)$$

By varying the frequency of the vibration, the sensor may be calibrated over its entire operating frequency range. The typical response of an unfiltered accelerometer is shown in Figure 11.



Figure 11. Typical Test Accelerometer Response

8.3 PCB CALIBRATION PROCEDURE

Numerous precautions are taken at PCB to insure accurate and repeatable results. This section provides a brief overview of the primary areas of concern.

Since the Back-to-Back Calibration technique relies on each sensor experiencing an identical acceleration level, proper mounting of the test sensor to the reference standard is imperative. Sensors with mounting holes are attached directly to the reference standard with a stud tightened to the recommended mounting torque. A shouldered mounting stud is typically used to prevent the stud from "bottoming out" in the hole. Both mounting surfaces are precision-machined and lapped to provide a smooth, flat interface according to the manufacturer's specification. A thin layer of silicone grease is placed between the mating surfaces to fill any imperfections and increase the mounting stiffness. The cables are stress-relieved by first routing them to the shaker head, then to a nearby stationary location. This reduces cable motion, which is especially important when testing charge output sensors, and helps to prevent extraneous motion or stresses from being imparted into the system. A typical set-up is shown in Figure 12.



Figure 12. Typical Calibration Set-Up

Adhesively mounted sensors use similar practices. However, in this case, a small portion of quick-bonding gel, or similar temporary adhesive, is used to attach the test sensor to a reference standard designed with a smooth, flat mounting surface.

In addition to mounting, the selection of the proper equipment is critical. Some of the more important considerations include: 1) the reference standard must be specified and previously calibrated over the frequency and/or amplitude range of interest; 2) the shaker should be selected to provide minimal transverse (lateral) motion and minimal distortion; and 3) the quality of the meters, signal generator, and other devices should be selected so as to operate within the limits of permissible error.

8.4 COMMON MISTAKES

Most calibration errors are caused by simply overlooking some of the fundamental principals of dynamics. This section attempts to address some of the more common concerns.

For stud-mount sensors, always mount the accelerometer directly to the reference standard. Ensure that the mounting surfaces are smooth, flat, and free of any burrs. Always use a coupling fluid, such as silicone grease, in the mounting interface to maintain a high mounting stiffness. Mount the sensor according to the manufacturer's recommended mounting torque. DO NOT use any intermediate mounting adaptors, as the mounted resonant frequency may be reduced, and thereby compromise the high-frequency performance. If necessary, use adaptor studs.



Figure 13. Stud Mounting

For adhesive mount sensors, use a thin, stiff layer of temporary adhesive such as quick-bonding gel or superglue. DO NOT use excessive amounts of glue or epoxy, as the mounting stiffness may be reduced and compromise highfrequency performance. It may also damage the sensor during removal.



Figure 14. Incorrect Adhesive Mounting

Triaxial accelerometers should always be mounted directly to the reference standard. Unless absolutely required, DO NOT use adaptors to re-orient the sensor along the axis of motion, as the mounting stiffness may be altered. The vibration at the test sensor's sensing element may differ from the vibration at the reference standard due to a "cantilever" effect, seen in Figure 15.



Figure 15. Mounting Triaxial Sensors (Incorrect)

Understand Back-to-Back Calibration limitations. Do not expect the uncertainty of calibration to be any better than $\pm 2\%$. (In fact, the uncertainty may be as high as $\pm 3\%$ or $\pm 4\%$ for frequencies <10 Hz or >2 kHz.) Since large sensors may affect high-frequency accuracy, verify that the test sensor does not mass load the reference standard. Validate your calibration system with another accelerometer prior to each calibration session. Check with the manufacturer for exact system specifications.

8.5 CONCLUSIONS

Without an adequate understanding of dynamics, determining what, when, and how to test a sensor is a difficult task. Therefore, each user must weigh the cost, time, and risk associated with self-calibration versus utilizing the services of an accredited laboratory.

9.0 SERVICE

See the supplement sheet, contained in this manual, for information on our warranty, service, repair, and return policies and instructions.

When unexpected measurement problems arise, call our 24-hour SensorLineSM to discuss your immediate dynamic instrumentation needs with a factory representative. Dial 716-684-0001.



3425 Walden Avenue, Depew, NY 14043-2495 USA Vibration Division toll-free 888-684-0013 24-hour SensorLineSM 716-684-0001 FAX 716-685-3886 E-mail vibration@pcb.com Website www.pcb.com

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ISO 9001 CERTIFIED

A2LA ACCREDITED to ISO 17025

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Printed in U.S



Model 352C68

ACCELEROMETER KIT

Installation and Operating Manual

For assistance with the operation of this product, contact the PCB Piezotronics, Inc.

Toll-free: 716-684-0001 24-hour SensorLine: 716-684-0001 Fax: 716-684-0987 E-mail: info@pcb.com Web: www.pcb.com







Repair and Maintenance

PCB guarantees Total Customer Satisfaction through its "Lifetime Warranty Plus" on all Platinum Stock Products sold by PCB and through its limited warranties on all other PCB Stock, Standard and Special products. Due to the sophisticated nature of our sensors and associated instrumentation, field servicing and repair is not recommended and, if attempted, will void the factory warranty.

Beyond routine calibration and battery replacements where applicable, our products require no user maintenance. Clean electrical connectors, housings, and mounting surfaces with solutions and techniques that will not harm the material of construction. Observe caution when using liquids near devices that are not hermetically sealed. Such devices should only be wiped with a dampened cloth—never saturated or submerged.

In the event that equipment becomes damaged or ceases to operate, our Application Engineers are here to support your troubleshooting efforts 24 hours a day, 7 days a week. Call or email with model and serial number as well as a brief description of the problem.

Calibration

Routine calibration of sensors and associated instrumentation is necessary to maintain measurement accuracy. We recommend calibrating on an annual basis, after exposure to any extreme environmental influence, or prior to any critical test.

PCB Piezotronics is an ISO-9001 certified company whose calibration services are accredited by A2LA to ISO/IEC 17025, with full traceability to SI through N.I.S.T. In addition to our standard calibration services, we also offer specialized tests, including: sensitivity at elevated or cryogenic temperatures, phase response, extended high or low frequency response, extended range, leak testing, hydrostatic pressure testing, and others. For more information, contact your local PCB Piezotronics distributor, sales representative, or factory customer service representative.

Returning Equipment

If factory repair is required, our representatives will provide you with a Return Material Authorization (RMA) number, which we use to reference any information you have already provided and expedite the repair process. This number should be clearly marked on the outside of all returned package(s) and on any packing list(s) accompanying the shipment.

Contact Information

PCB Piezotronics, Inc. 3425 Walden Ave. Depew, NY14043 USA Toll-free: (800) 828-8840 24-hour SensorLine: (716) 684-0001 General inquiries: <u>info@pcb.com</u> Repair inquiries: <u>rma@pcb.com</u>

For a complete list of distributors, global offices and sales representatives, visit our website, <u>www.pcb.com</u>.

Safety Considerations

This product is intended for use by qualified personnel who recognize shock hazards and are familiar with the precautions required to avoid injury. While our equipment is designed with user safety in mind, the protection provided by the equipment may be impaired if equipment is used in a manner not specified by this manual.

Discontinue use and contact our 24-Hour Sensorline if:

- Assistance is needed to safely operate equipment
- Damage is visible or suspected
- Equipment fails or malfunctions

For complete equipment ratings, refer to the enclosed specification sheet for your product.

Definition of Terms and Symbols

The following symbols may be used in this manual:



DANGER

Indicates an immediate hazardous situation, which, if not avoided, may result in death or serious injury.



CAUTION

Refers to hazards that could damage the instrument.



NOTE

Indicates tips, recommendations and important information. The notes simplify processes and contain additional information on particular operating steps.

The following symbols may be found on the equipment described in this manual:



This symbol on the unit indicates that high voltage may be present. Use standard safety precautions to avoid personal contact with this voltage.



This symbol on the unit indicates that the user should refer to the operating instructions located in the manual.



This symbol indicates safety, earth ground.



PCB工业监视和测量设备 - 中国RoHS2公布表 PCB Industrial Monitoring and Measuring Equipment - China RoHS 2 Disclosure Table

	有害物 质							
部件名称	铅 (Pb)	汞 (Hg)	镉 (Cd)	六价铬 (Cr(VI))	多溴 联苯 (PBB)	多溴二苯 醚 (PBDE)		
住房	0	0	0	0	0	0		
PCB板	Х	0	0	0	0	0		
电气连接 器	0	0	0	0	0	0		
压电晶 体	Х	0	0	0	0	0		
环氧	0	0	0	0	0	0		
铁氟龙	0	0	0	0	0	0		
电子	0	0	0	0	0	0		
厚膜基板	0	0	Х	0	0	0		
电线	0	0	0	0	0	0		
电缆	х	0	0	0	0	0		
塑料	0	0	0	0	0	0		
焊接	Х	0	0	0	0	0		
铜合金 /黄 铜	Х	0	0	0	0	0		
本表格依据 SJ/T 11364 的规定编制。								
O:表示该有害物质在该部件所有均质材料中的含量均在 GB/T 26572 规定的限量要求以下。								
X:表示该有害物质至少在该部件的某一均质材料中的含量超出 GB/T 26572 规定的限量要求。								
铅是欧洲RoHS指名	令2011/65/ E	J附件三	和附件四	目前由于允 许的豁	免。			

CHINA ROHS COMPLIANCE

Hazardous Substances								
Lead (Pb)	Mercury (Hg)	Cadmium (Cd)	Chromium VI Compounds (Cr(VI))	Polybrominated Biphenyls (PBB)	Polybrominated Diphenyl Ethers (PBDE)			
0	0	0	0	0	0			
Х	0	0	0	0	0			
0	0	0	0	0	0			
Х	0	0	0	0	0			
0	0	0	0	0	0			
0	0	0	0	0	0			
0	0	0	0	0	0			
0	0	Х	0	0	0			
0	0	0	0	0	0			
Х	0	0	0	0	0			
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Х	0	0	0	0	0			
Х	0	0	0	0	0			
	Lead (Pb)	Lead (Pb) Mercury (Hg) 0 0 0 0 X 0 0 0 X 0 0 0 X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 X 0 X 0 X 0 X 0	Lead (Pb) Mercury (Hg) Cadmium (Cd) 0 0 0 0 0 0 X 0 0 X 0 0 X 0 0 X 0 0 0 0 0 X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 X 0 0 X 0 0 X 0 0	Hazerdous SubstancesLead (Pb)Mercury (Hg)Cadmium (Cd)Chromium VI Compounds (r(VI))000000001000010000100001000010000100001000010000100100100100100001000010000100001100012000130001400015000	Hazardous ConstructionHarcury (Hg)Cadmium (Cd)Chromium VI Compounds (Cr(VI))Polybrominated Biphenyls (PBB) (Cr(VI))000000000010			

This table is prepared in accordance with the provisions of SJ/T 11364.

O: Indicates that said hazardous substance contained in all of the homogeneous materials for this part is below the limit requirement of GB/T 26572.

X: Indicates that said hazardous substance contained in at least one of the homogeneous materials for this part is above the limit requirement of GB/T 26572.

Lead is present due to allowed exemption in Annex III or Annex IV of the European RoHS Directive 2011/65/EU.

General OPERATING GUIDE

for use with

PIEZOELECTRIC ICP[®] ACCELEROMETERS

SPECIFICATION SHEET, INSTALLATION DRAWING AND CALIBRATION INFORMATION ENCLOSED

PCB ASSUMES NO RESPONSIBILITY FOR DAMAGE CAUSED TO THIS PRODUCT AS A RESULT OF PROCEDURES THAT ARE INCONSISTENT WITH THIS OPERATING GUIDE.

1.0 INTRODUCTION

Congratulations on the purchase of a quality, ICP[®] acceleration sensor. In order to ensure the highest level of performance for this product, it is imperative that you properly familiarize yourself with the correct mounting and installation techniques before attempting to operate this device. If, after reading this manual, you have any additional questions concerning this sensor or its application, feel free to call a factory Application Engineer at 716-684-0001 or your nearest PCB sales representative.

2.0 ICP[®] ACCELEROMETERS

Powered by simple, inexpensive, constant-current signal conditioners, these sensors are easy to operate and interface with signal analysis, data acquisition and recording instruments. The following features further characterize ICP^{\circledast} sensors:

- Fixed voltage sensitivity, regardless of cable type or length.
- Low-impedance output signal, which can be transmitted over long cables in harsh environments with virtually no loss in signal quality.
- Two-wire operation with low cost coaxial cable, twoconductor ribbon wire or twisted-pair cabling.
- Low-noise, voltage-output signal compatible with standard readout, signal analysis, recording, and data acquisition equipment.
- Low cost per-channel ICP[®] accelerometers require only an inexpensive, constant-current signal conditioner to operate.

• Intrinsic self-test feature – monitoring the sensor's output bias voltage provides an indication of proper operation, faulty condition, and bad cables.

In the rear of this manual you will find a **Specification Sheet**, which provides the complete performance characteristics of your particular sensor.

3.0 OPTIONAL FEATURES

Many sensors are supplied with standard, optional features. When listed before the model number, the following prefix letters indicate that the sensor is manufactured or supplied with a particular optional feature: "A" option: adhesive mount; "HT" option: extended high temperature range; "J" option: electrically ground isolated; "M" option: metric mounting thread; "Q" option: extended discharge time constant; "T" option: built-in transducer electronic data sheet (TEDS); and "W" option: attached, water-resistant cabling. Other prefix letters, such as "K", "KR", "GK", "GKR", "KL", and "GKL", indicate that the sensor is ordered in kit form, including interconnect cabling and signal conditioner. If you have any questions or concerns regarding optional features, consult the Vibration Division's product catalog or contact a PCB factory representative.

4.0 INSTALLATION OVERVIEW

When choosing a mounting method, consider closely both the advantages and disadvantages of each technique. Characteristics like location, ruggedness, amplitude range, accessibility, temperature, and portability are extremely critical. However, the most important and often overlooked consideration is the effect the mounting technique has on the high-frequency performance of the accelerometer.

[®] ICP is a registered trademark of PCB Group, Inc., which uniquely identifies PCB sensors that incorporate built-in microelectronics.

Shown in figure 1 are six possible mounting techniques and their effects on the performance of a typical piezoelectric accelerometer. (Note that not all of the mounting methods may apply to your particular sensor). The mounting configurations and corresponding graph demonstrate how the high-frequency response of the accelerometer may be compromised as mass is added to the system and/or the mounting stiffness is reduced.

NOTE: The low-frequency response is unaffected by the mounting technique. This roll-off behavior is typically fixed by the sensor's built-in electronics. However, when operating AC-coupled signal conditioners with readout devices having an input impedance of less than one megohm, the low frequency range may be affected. If necessary, contact a factory representative for further assistance.



Figure 1. Assorted Mounting Configurations and Their Effects on High Frequency

4.1 STUD MOUNT

This mounting technique requires smooth, flat contact surfaces for proper operation and is recommended for permanent and/or secure installations. Stud mounting is also recommended when testing at high frequencies.

NOTE: Do NOT attempt mounting on curved, rough, or uneven surfaces, as the potential for misalignment and limited contact surface may significantly reduce the sensor's upper operating frequency range.

STEP 1: First, prepare a smooth, flat mounting surface, then drill and tap a mounting hole in the center of this area as shown in Figure 2 and in accordance with the enclosed **Installation Drawing**.



Figure 2. Mounting Surface Preparation

A precision-machined mounting surface with a minimum finish of 63 μ in (0.00016 mm) is recommended. (If it is not possible to properly prepare the test structure mounting surface, consider adhesive mounting as a possible alternative). Inspect the area, checking that there are no burrs or other foreign particles interfering with the contact surface.

STEP 2: Wipe clean the mounting surface and spread on a light film of grease, oil, or similar coupling fluid prior to installation.



Figure 3. Mounting Surface Lubrication

Adding a coupling fluid improves vibration transmissibility by filling small voids in the mounting surface and increasing the mounting stiffness. For semipermanent mounting, substitute epoxy or another type of adhesive.

STEP 3: Screw the mounting stud into the base of accelerometer and hand-tighten (this step is unnecessary for units having an integral mounting stud). Then, screw the sensor into the tapped hole that was prepared in the test object. Tighten the unit in place by applying, with a torque wrench, the recommended mounting torque, as listed on the enclosed **Installation Drawing**.

NOTE: It is important to use a torque wrench during this step. Under-torquing the sensor may not adequately couple the device; over-torquing may result in stud failure.

4.2 ADHESIVE MOUNT

Adhesive mounting is often used for temporary installation or when the test object surface cannot be adequately prepared for stud mounting. Adhesives like hot glue and wax perform well for temporary installations whereas two-part epoxies and quick-bonding gels (super glue) provide a more permanent installation. Two techniques are used for adhesive mounting; they are via an adhesive mounting base (method 1 below) or direct adhesive mounting (method 2 below).

NOTE: Adhesively mounted sensors often exhibit a reduction in high-frequency range. Generally, smooth surfaces and stiff adhesives provide the best high frequency response.

METHOD 1 - Adhesive Mounting Base

This method involves attaching a base to the test structure, then securing the sensor to the base. This allows for easy removal of the accelerometer. Also, since many bases are manufactured of "hard-coated" aluminum, they provide electrical isolation to eliminate ground loops and reduce electrical interference that may propagate from the surface of the test object.

STEP 1: Prepare a smooth, flat mounting surface. A minimum surface finish of 63 μ in (0.00016 mm) generally works best.

STEP 2: Stud-mount the sensor to the flat side of the appropriate adhesive mounting base according to the guidelines set forth in **STEPS 2** and **3** of the Stud Mount Procedure presented above.

STEP 3: Place a small portion of adhesive on the underside of the mounting base (the underside is discernable by the concentric grooves which are designed to accept the adhesive). Firmly press down on the assembly to displace any extra adhesive remaining under the base.



Figure 4. Mounting Base: Adhesive Installation

METHOD 2 - Direct Adhesive Mount

For restrictions of space or for convenience, most sensors can be adhesive-mounted directly to the test structure (an exception being units having integral mounting studs).

STEP 1: Prepare a smooth, flat mounting surface. A minimum surface finish of 63 μ in (0.00016 mm) generally works best.

STEP 2: Place a small portion of adhesive on the underside of the sensor. Firmly press down on the top of the assembly to displace any adhesive. Be aware that

excessive amounts of adhesive can make sensor removal difficult. Also, adhesive that may invade the tapped mounting hole in the base of the sensor will compromise future ability to stud mount the unit.



Figure 5. Direct Adhesive Mounting

4.2-1 ADHESIVE MOUNT REMOVAL (other than wax)

NOTE: A debonder should always be used to avoid sensor damage.

To avoid damaging the accelerometer, a debonding agent must be applied to the adhesive prior to sensor removal. With so many adhesives in use (everything from super glues, dental cement, epoxies, etc), there is no universal debonding agent available. The debonder for the Loctite 454 adhesive that PCB offers is Acetone. If you are using anything other than Loctite 454, you will have to check with the individual manufacturers for their debonding recommendations. The debonding agent must be allowed to penetrate the surface in order to properly react with the adhesive, so it is advisable to wait a few minutes before removing the sensor.

After the debonding agent has set, you can use an ordinary open-end wrench if the accelerometer has a hex base or square base, or the supplied removal tool for teardrop accelerometers. After attaching either, use a gentle shearing (or twisting) motion (by hand only) to remove the sensor from the test structure.

4.3 MAGNETIC MOUNT

Magnetic mounting provides a convenient means for making quick, portable measurements and is commonly used for machinery condition monitoring, predictive maintenance, spot checks, and vibration trending applications.

NOTE: The correct magnet choice and an adequately prepared mounting surface are critical for obtaining reliable measurements, especially at high frequencies. Poor installations can cause as much as a 50% drop in the sensor frequency range.

Not every magnet is suitable for all applications. For example, rare earth magnets are commonly used because

of their high strength. Flat magnets work well on smooth, flat surfaces, while dual-rail magnets are required for curved surfaces such as motor housings and pipes. In the case of non-magnetic or rough surfaces, it is recommended that the user first weld, epoxy, or otherwise adhere a steel mounting pad to the test surface. This provides a smooth location for mounting and a target to insure that subsequent measurements for trending purposes are taken at the same location.



Figure 6. Magnet Types

STEP 1: Prepare a smooth, flat mounting surface. A minimum surface finish of 63 μ in (0.00016 mm) generally works best. After cleaning the surface and checking for burrs, apply a light film of silicone grease, machine oil, or similar-type coupling fluid.

STEP 2: After choosing the correct magnet type, inspect the magnet, verifying that its mounting surfaces are flat and smooth.

STEP 3: Stud-mount the accelerometer to the appropriate magnet according to the guidelines set forth in **STEP 3** of the above Stud Mount Procedure.

STEP 4: To avoid damage to the sensor, install the magnet/sensor assembly to the prepared test surface by gently "rocking" or "sliding" it into place.



Figure 7. Magnet Mounting

CAUTION: Magnetically mounting of an accelerometer has the potential to generate very high (and very damaging) acceleration (g) levels. To prevent such damage, exercise caution and install the assembly gently by rocking it into place. If shock is expected to be a particular concern, use a sensor with built-in shock protection. For further assistance, contact a factory representative.

4.4 HANDHELD OR PROBE TIP MOUNT

This method is NOT recommended for most applications. Both the accuracy and repeatability at low (<5 Hz) and high frequency (>1 kHz) ranges are questionable. It is generally used only for machinery condition monitoring, when installation space is restricted, or other portable trending applications. The technique, however, can be useful for initially determining locations of greatest vibration to establish a permanent sensor installation point.

5.0 CABLING

Care and attention to cable installation and cable condition is essential as the reliability and accuracy of any measurement system is no better than that of its weakest link. Do to the nature of vibration measurements, all sensor cables will ultimately fatigue and fail. Good installation practice will extend the life of a cable, however, it is highly recommended to keep spare cables on hand to enable continuation of the test in the event of a cable failure.

STEP 1: Ascertain that you have the correct cable type.

One cable type cannot satisfy all applications. ICP® sensors can be operated with any ordinary two-wire or coaxial cable. Special, low-noise cables that are typically recommended for use with high-impedance, charge-output sensors can also be used. For applications requiring conformity to $\mathbf{C}\mathbf{\epsilon}$, low noise cables are essential. Industrial applications often require shielded, twisted-pair cables to reduce the effects of EMI and RFI that is present near electrical motors and machinery. Teflon-jacketed cabling may be necessary to withstand corrosive environments and higher temperatures. Consult the Vibration Division's product catalog for more information about cables or feel free to contact a factory representative for a specific recommendation on cables that are best suited for your application.

STEP 2: Connect the cable to the accelerometer.

A small amount of thread-locking compound placed on the connector threads prior to attachment helps secure the cable during testing. In wet, oily, or dirty environments, the connection can be sealed with silicone rubber sealant, O-rings, and flexible, heat-shrink tubing.

Coaxial Cables: Make connection by inserting the cable's connector pin into the sensor's mating socket. Then thread the connector into place by turning the cable connector's outer shell onto the accelerometer's electrical connector.

NOTE: Do not spin the accelerometer while holding the cable connector stationary, as this will cause undue

friction on the center pin of the cable connector and lead to premature fatigue.

Multi-pin connectors: Make connection by inserting the sensor's mating pins onto the cable connector's mating sockets. Then thread the connector into place by turning the cable connector's outer shell onto the accelerometer's electrical connector.

Pigtail Connections: Certain miniature accelerometers and shock sensors are provided with lightweight cables attached to "Pigtail" connections. This type of connection reduces overall weight and incidence of connection intermittency under shock conditions. In the event of a cable or connection failure, the cables may be repaired in the field simply by re-soldering the stripped leads to the exposed pins on the sensor. (Check the **Installation Drawing** to determine signal and ground pins). In many cases, it is also helpful to protect the solder joint with heat-shrink tubing or epoxy.

NOTE: If you do not have the experience or resources to attach pigtail leads, consult PCB to discuss factory attachment. Damage to internal electronics may be caused by excessive heat during soldering and such failure is not covered by warranty.

STEP 3: Route the cable to the signal conditioner, making certain to relieve stress on the sensor/cable connection. Also, minimize cable motion by securing it with tape, clamps or ties at regular intervals.

Common sense should be used to avoid physical damage and minimize electrical noise. For instance, avoid routing cables near high-voltage wires. Do not route cables along floors or walkways where they may be stepped on or become contaminated. To avoid ground loops, shielded cables should have the shield grounded at one end only, typically at the signal conditioner.

STEP 4: Finally, connect the remaining cable end to the signal conditioner. It is good practice to dissipate any electrical charge that may have accumulated in the cable by shorting the signal pin to the ground pin or shell prior to attachment.

6.0 POWERING

All ICP^{\circledast} sensors require constant current excitation for proper operation. For this reason, use only PCB constantcurrent signal conditioners or other approved constantcurrent sources. A typical system schematic is shown in Figure 8.

NOTE: Damage to the built-in electronics resulting from the application of incorrect power, or the use of an unapproved power source, is NOT covered by warranty.



Figure 8. Typical System Schematic

The power supply consists of a current-regulated, 18 to 30 VDC source. This power is regulated by a current-limiting circuit, which provides the constant-current excitation required for proper operation of ICP[®] sensors. In general, battery-powered devices offer versatility for portable, low-noise measurements, whereas line-powered units provide the capability for continuous monitoring. Consult the Vibration Division's product catalog for more information about signal conditioners.

NOTE: Under no circumstances should a voltage be supplied to an ICP[®] accelerometer without a current-regulating diode or equivalent electrical circuit. This may include ohmmeters, multi-meters and continuity testers.

Meters or LEDs are used on PCB signal conditioners to monitor the bias voltage on the sensor output signal, to check sensor operation, and detect cable faults. Normally, a "yellow" reading indicates an open circuit; "green" indicates normal operation; and "red" indicates either a short or overload condition. Finally, a capacitor at the output stage of the device removes the sensor output bias voltage from the measurement signal. This provides a zero-based, AC-coupled output signal that is compatible with most standard readout devices.

NOTE: Units having a low bias voltage may be in the "red," when actually they are working properly. If suspect, the bias voltage can be checked with a voltmeter attached to a "T" connector installed on the input connector to the signal conditioner.

Note: For readout devices having an input impedance near one gigohm (as encountered with some A to D converters), it may be necessary to place a one megohm resistor in parallel to the readout input to eliminate slow turn-on and signal drift.

Today, many FFT analyzers, data acquisition modules, and data collectors have the proper constant-current excitation built-in for direct use with ICP[®] sensors. Before using this feature, however, check that the supply voltage and constant current are within acceptable limits for use with your particular sensor. (Check enclosed **Specification Sheet**). Please contact the respective signal conditioner manufacturer or check the product manual for more information.

7.0 OPERATING

After completing the system setup, switch on the signal conditioner and allow 1 to 2 minutes for the system to stabilize. The meter (or LED) on the signal conditioner should be reading "green." This indicates proper operation and you may begin taking measurements. If a faulty condition is indicated (red or yellow reading), first check all system connections, then check the functionality of the cable and signal conditioner. If the system still does not operate properly, consult a PCB factory representative.

NOTE: Always operate the accelerometer within the limitations listed on the enclosed **Specification Sheet**. Operating the device outside these parameters can cause temporary or permanent damage to the sensor.

8.0 ACCELEROMETER CALIBRATION

Accelerometer calibration provides, with a definable degree of accuracy, the necessary link between the physical quantity being measured and the electrical signal generated by the sensor. In addition, other useful information concerning operational limits, physical parameters, electrical characteristics, or environmental influences may also be determined. Without this link, analyzing data becomes a nearly impossible task. Fortunately, most sensor manufacturers provide a calibration record that documents the exact characteristics of each sensor. (The type and amount of data varies depending on the manufacturer, sensor type, contractual regulations, and other special requirements).

Under normal conditions, piezoelectric sensors are extremely stable, and their calibrated performance characteristics do not change over time. However, the sensor may be temporarily or permanently affected by harsh environments influences or other unusual conditions that may cause the sensor to experience dynamic phenomena outside of its specified operating range. This change manifests itself in a variety of ways, including: a shift of the sensor resonance due to a cracked crystal; a temporary loss of low-frequency measuring capability due to a drop in insulation resistance; or total failure of the built-in microelectronic circuit due to a high mechanical shock.

For these reasons, it is recommended that a recalibration cycle be established for each accelerometer. This schedule is unique and is based on a variety of factors, such as: extent of use, environmental conditions, accuracy requirements, trend information obtained from previous calibration records, contractual regulations, frequency of "crosschecking" against other equipment, manufacturer recommendation, and any risk associated with incorrect readings. International standards, such as ISO 10012-1, provide insight and suggest methods for determining recalibration intervals for most measuring equipment. With the above information in mind and under "normal" circumstances, PCB conservatively suggests a 12- to 24-month recalibration cycle for most piezoelectric accelerometers.

NOTE: It is good measurement practice to verify the performance of each accelerometer with a Handheld Shaker or other calibration device before and after each measurement. The PCB Handheld Shaker operates at a fixed frequency and known amplitude (1.0 g) to provide a quick check of sensor sensitivity.

8.1 RECALIBRATION SERVICE

PCB offers recalibration services for our piezoelectric accelerometers, as well as units produced by other manufacturers. Our internal metrology laboratory is certified to ISO 9001, accredited by A2LA to ANSI/IEC 17025 and ANSI/NCSL Z540-1, complies with ISO 10012-1 (and former MIL-STD-45662A), and uses equipment directly traceable to NIST. Our investment in equipment, traceability and conformance to industry standards ensures accurate calibration against relevant specifications, in a timely fashion.

8.2 BACK-TO-BACK CALIBRATION THEORY

Many companies choose to purchase the equipment necessary to perform the recalibration procedure in house. While this may result in both a savings of time and money, it has also been attributed to incorrect readings and costly errors. Therefore, in an effort to prevent the common mistakes associated with customer-performed calibration, this document includes a broad overview of the Back-to-Back Calibration technique. This technique provides a quick and easy method for determining the sensitivity of a test accelerometer over a wide frequency range.

Back-to-Back Calibration is perhaps the most common method for determining the sensitivity of piezoelectric accelerometers. This method relies on a simple comparison to a previously calibrated accelerometer, typically referred to as a reference standard.



Figure 9. Reference Standard Accelerometer

These high-accuracy devices, which are directly traceable to a recognized standards laboratory, are designed for stability, as well as configured to accept a test accelerometer. By mounting a test accelerometer to the reference standard and then connecting this combination to a suitable vibration source, it is possible to vibrate both devices and compare the data as shown in Figure 10. (Test set-ups may be automated and vary, depending on the type and number of accelerometers being calibrated).



Figure 10. Typical Back-to-Back Calibration System

Because the acceleration is the same on both sensors, the ratio of their outputs (V_T/V_R) must also be the ratio of their sensitivities. With the sensitivity of the reference standard (S_R) known, the exact sensitivity of the test sensor (S_T) is easily calculated by using the following equation:

$$S_T = S_R (V_T / V_R)$$

By varying the frequency of the vibration, the sensor may be calibrated over its entire operating frequency range. The typical response of an unfiltered accelerometer is shown in Figure 11.



Figure 11. Typical Test Accelerometer Response

8.3 PCB CALIBRATION PROCEDURE

Numerous precautions are taken at PCB to insure accurate and repeatable results. This section provides a brief overview of the primary areas of concern.

Since the Back-to-Back Calibration technique relies on each sensor experiencing an identical acceleration level, proper mounting of the test sensor to the reference standard is imperative. Sensors with mounting holes are attached directly to the reference standard with a stud tightened to the recommended mounting torque. A shouldered mounting stud is typically used to prevent the stud from "bottoming out" in the hole. Both mounting surfaces are precision-machined and lapped to provide a smooth, flat interface according to the manufacturer's specification. A thin layer of silicone grease is placed between the mating surfaces to fill any imperfections and increase the mounting stiffness. The cables are stress-relieved by first routing them to the shaker head, then to a nearby stationary location. This reduces cable motion, which is especially important when testing charge output sensors, and helps to prevent extraneous motion or stresses from being imparted into the system. A typical set-up is shown in Figure 12.



Figure 12. Typical Calibration Set-Up

Adhesively mounted sensors use similar practices. However, in this case, a small portion of quick-bonding gel, or similar temporary adhesive, is used to attach the test sensor to a reference standard designed with a smooth, flat mounting surface.

In addition to mounting, the selection of the proper equipment is critical. Some of the more important considerations include: 1) the reference standard must be specified and previously calibrated over the frequency and/or amplitude range of interest; 2) the shaker should be selected to provide minimal transverse (lateral) motion and minimal distortion; and 3) the quality of the meters, signal generator, and other devices should be selected so as to operate within the limits of permissible error.

8.4 COMMON MISTAKES

Most calibration errors are caused by simply overlooking some of the fundamental principals of dynamics. This section attempts to address some of the more common concerns.

For stud-mount sensors, always mount the accelerometer directly to the reference standard. Ensure that the mounting surfaces are smooth, flat, and free of any burrs. Always use a coupling fluid, such as silicone grease, in the mounting interface to maintain a high mounting stiffness. Mount the sensor according to the manufacturer's recommended mounting torque. DO NOT use any intermediate mounting adaptors, as the mounted resonant frequency may be reduced, and thereby compromise the high-frequency performance. If necessary, use adaptor studs.



Figure 13. Stud Mounting

For adhesive mount sensors, use a thin, stiff layer of temporary adhesive such as quick-bonding gel or superglue. DO NOT use excessive amounts of glue or epoxy, as the mounting stiffness may be reduced and compromise highfrequency performance. It may also damage the sensor during removal.



Figure 14. Incorrect Adhesive Mounting

Triaxial accelerometers should always be mounted directly to the reference standard. Unless absolutely required, DO NOT use adaptors to re-orient the sensor along the axis of motion, as the mounting stiffness may be altered. The vibration at the test sensor's sensing element may differ from the vibration at the reference standard due to a "cantilever" effect, seen in Figure 15.



Figure 15. Mounting Triaxial Sensors (Incorrect)

Understand Back-to-Back Calibration limitations. Do not expect the uncertainty of calibration to be any better than $\pm 2\%$. (In fact, the uncertainty may be as high as $\pm 3\%$ or $\pm 4\%$ for frequencies <10 Hz or >2 kHz.) Since large sensors may affect high-frequency accuracy, verify that the test sensor does not mass load the reference standard. Validate your calibration system with another accelerometer prior to each calibration session. Check with the manufacturer for exact system specifications.

8.5 CONCLUSIONS

Without an adequate understanding of dynamics, determining what, when, and how to test a sensor is a difficult task. Therefore, each user must weigh the cost, time, and risk associated with self-calibration versus utilizing the services of an accredited laboratory.

9.0 SERVICE

See the supplement sheet, contained in this manual, for information on our warranty, service, repair, and return policies and instructions.

When unexpected measurement problems arise, call our 24-hour SensorLineSM to discuss your immediate dynamic instrumentation needs with a factory representative. Dial 716-684-0001.



3425 Walden Avenue, Depew, NY 14043-2495 USA Vibration Division toll-free 888-684-0013 24-hour SensorLineSM 716-684-0001 FAX 716-685-3886 E-mail vibration@pcb.com Website www.pcb.com

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Manual Number: 18292 Manual Revision: B ECN Number: 19829 VIB-ICPMANUAL-09

Printed in U.S

Model Number

ICP® ACCELEROMETER

Revision: N

352C68		IC IC	PRACCEL	ERU	PIVIEIER		ECN #: 31827
Performance		ENGLISH	SI		OPTION		
Sensitivity(+ 10 %)		100 mV/a	$10.2 \text{ mV}/(\text{m/s}^2)$		Optional versions have identical specification	ons and accessories as lis	sted for the standard model
Measurement Pange		+ 50 g pk	+ 491 m/s ² nk		except where noted below.	. More than one option ma	av be used.
Frequency Range + 5 %)	0.5 to 10.000 Hz	0.5 to 10.000 Hz				
Frequency Range(± 0 %)) %)	0.3 to 12,000 Hz	0.3 to 12 000 Hz		A - Adhesive Mount		
Frequency Range(± 3 dF	3)	0.2 to 20.000 Hz	0.2 to 20.000 Hz		Supplied Accessory : Model 080A90 Quick	Bonding Gel (1) replaces	Model 080A15
Resonant Frequency	-,	≥ 35 kHz	≥ 35 kHz				
Phase Response(± 5 °)(a	at 70°F [21°C])	2 to 6000 Hz	2 to 6000 Hz		HT - High temperature, extends normal op	peration temperatures	
Broadband Resolution(1	to 10,000 Hz)	0.00016 g rms	0.0015 m/s ² rms	[1]	Frequency Range(5%)	5 to 10,000 Hz	5 to 10,000
Non-Linearity	. ,	≤ 1 %	≤ 1 %	[3]	Frequency Range(10 %)	3 to 12,000 Hz	3 to 12,000
Transverse Sensitivity		≤ 5 %	≤ 5 %	[4]	Frequency Range(3 dB)	2 to 20,000 Hz	2 to 20,000
Environmental					Broadband Resolution(1 to 10,000 Hz)	0.0002 g rms	0.002 m/s ² rms
Overload Limit(Shock)		± 5000 g pk	± 49,050 m/s ² pk		Temperature Range(Operating)	-65 to +250 °F	-54 to +121 °C
Temperature Range(Ope	erating)	-65 to +200 °F	-53 to +93 °C	[2]	Discharge Time Constant	0.08 to 0.24 sec	0.08 to 0.24 sec
Temperature Response		See Graph	See Graph	[1]	Spectral Noise(1 Hz)	75 µg/√Hz	736 (µm/sec²)/√Hz
Base Strain Sensitivity		≤ 0.005 g/με	≤ 0.05 (m/s²)/με	[1]	Spectral Noise(10 Hz)	25 µg/√Hz	245 (µm/sec²)/√Hz
Electrical							
Excitation Voltage		18 to 30 VDC	18 to 30 VDC		J - Ground Isolated		
Constant Current Excitat	tion	2 to 20 mA	2 to 20 mA		Frequency Range(5%)	0.5 to 8000 Hz	0.5 to 8000 Hz
Output Impedance		≤ 300 ohm	≤ 300 ohm		Frequency Range(10 %)	0.3 to 10,000 Hz	0.3 to 10,000 Hz
Output Bias Voltage		8 to 12 VDC	8 to 12 VDC		Frequency Range(3 dB)	0.2 to 16,000 Hz	0.2 to 16,000 Hz
Discharge Time Constan		0.8 to 2.4 sec	0.8 to 2.4 sec		Resonant Frequency	≥ 30 kHz	≥ 30 kHz
Setting Time(within 10%			<10 Sec	[1]	Electrical Isolation(Base)	≥ 10° ohm	≥ 10° ohm
Spectral Noise(1 Hz)			588 (µm/sec ⁻)/vHz	[1]	Size - Hex x Height	3/8 in x 0.75 in	3/8 in x 19.1 mm
Spectral Noise(10 Hz)		To µg/VHz	157 (µm/sec-)/vHz	[1]	Weight	0.1 oz	2.8 gm
Spectral Noise(100 Hz)		5 µg/vHz	49 (µm/sec ²)/vHz	[1]	M. Matrix Mauri		
Spectral Noise(1 KHZ)		1.5 µg/vHz	14.7 (µm/sec ²)/vHz	LU.	We - Metric Mount	M2 x 0 50 Mala	M2 × 0 E0 Molo
Physical		Oie	Commin		Supplied Accessory : Model M080A15 Adb	M3 X U.50 Male	m3 x 0.50 male
Sensing Element		Ceramic	Ceramic		Supplied Accessory , model motora to Adr	icolve would in g base (1)	replaces model book to
Sensing Geometry		Titanium	Titopium		W - Water Resistant Cable		
Soaling Wateria		Welded Hermetic	Welded Hermetic		Electrical Connector	Sealed Integral Cable	Sealed Integral Cable
Size (Hex x Height)		9/32 in x 0.73 in	9/32 in x 18 5 mm		Electrical Connection Position	Side	Side
Weight		0.070.07	2.0 am	[1]			
Electrical Connector		10-32 Coaxial Jack	10-32 Coaxial Jack				
Electrical Connection Po	sition	Тор	Тор		NOTES:		
Mounting Thread		5-40 Male	5-40 Male		[1] Typical.		
Mounting Torque		8 to 12 in-lb	90 to 135 N-cm		[2] 200°F to 250°F data valid with H I option	n only.	
					[4] Transverse sensitivity is typically $\leq 3\%$.	method.	
	<u>۾</u>	Typical Sensitivity Devi	ation vs Temperature		[5] See PCB Declaration of Conformance F	PS023 for details.	
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	iti	20					
	a Ma	10			Model 0804109 Petro Way (1)		
	ă	0			Model 080A15 Adhesive Mounting Base (1	}	
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All specifications are at n	oom temperature unless otherwi	se specified					
In the interest of constant	t product improvement, we resei	ve the right to change speci	fications without notice.				
ICP [®] is a registered trade	emark of PCB Group Inc					Phone	: 716-684-0001
	since of the bold					Fax: 7	6-685-3886
					VIBRATION DIV	ASION E-Mail:	vibration@pcb.com
					3425 Walden Avenue, Depew, NY 14043		



Model 352B10

Miniature, lightweight (0.7 gm), ceramic shear ICP® accel., 10 mV/g, 2 to

Installation and Operating Manual

For assistance with the operation of this product, contact PCB Piezotronics, Inc.

Toll-free: 800-828-8840 24-hour SensorLine: 716-684-0001 Fax: 716-684-0987 E-mail: info@pcb.com Web: www.pcb.com







Repair and Maintenance

PCB guarantees Total Customer Satisfaction through its "Lifetime Warranty Plus" on all Platinum Stock Products sold by PCB and through its limited warranties on all other PCB Stock, Standard and Special products. Due to the sophisticated nature of our sensors and associated instrumentation, field servicing and repair is not recommended and, if attempted, will void the factory warranty.

Beyond routine calibration and battery replacements where applicable, our products require no user maintenance. Clean electrical connectors, housings, and mounting surfaces with solutions and techniques that will not harm the material of construction. Observe caution when using liquids near devices that are not hermetically sealed. Such devices should only be wiped with a dampened cloth—never saturated or submerged.

In the event that equipment becomes damaged or ceases to operate, our Application Engineers are here to support your troubleshooting efforts 24 hours a day, 7 days a week. Call or email with model and serial number as well as a brief description of the problem.

Calibration

Routine calibration of sensors and associated instrumentation is necessary to maintain measurement accuracy. We recommend calibrating on an annual basis, after exposure to any extreme environmental influence, or prior to any critical test.

PCB Piezotronics is an ISO-9001 certified company whose calibration services are accredited by A2LA to ISO/IEC 17025, with full traceability to SI through N.I.S.T. In addition to our standard calibration services, we also offer specialized tests, including: sensitivity at elevated or cryogenic temperatures, phase response, extended high or low frequency response, extended range, leak testing, hydrostatic pressure testing, and others. For more information, contact your local PCB Piezotronics distributor, sales representative, or factory customer service representative.

Returning Equipment

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Contact Information

PCB Piezotronics, Inc. 3425 Walden Ave. Depew, NY14043 USA Toll-free: (800) 828-8840 24-hour SensorLine: (716) 684-0001 General inquiries: <u>info@pcb.com</u> Repair inquiries: <u>rma@pcb.com</u>

For a complete list of distributors, global offices and sales representatives, visit our website, <u>www.pcb.com</u>.

Safety Considerations

This product is intended for use by qualified personnel who recognize shock hazards and are familiar with the precautions required to avoid injury. While our equipment is designed with user safety in mind, the protection provided by the equipment may be impaired if equipment is used in a manner not specified by this manual.

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- Damage is visible or suspected
- Equipment fails or malfunctions

For complete equipment ratings, refer to the enclosed specification sheet for your product.

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The following symbols may be used in this manual:



DANGER

Indicates an immediate hazardous situation, which, if not avoided, may result in death or serious injury.



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Refers to hazards that could damage the instrument.



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Indicates tips, recommendations and important information. The notes simplify processes and contain additional information on particular operating steps.

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PCB工业监视和测量设备 - 中国RoHS2公布表 PCB Industrial Monitoring and Measuring Equipment - China RoHS 2 Disclosure Table

	有害物 质							
部件名称	铅 (Pb)	汞 (Hg)	镉 (Cd)	六价铬 (Cr(VI))	多溴 联苯 (PBB)	多溴二苯 醚 (PBDE)		
住房	0	0	0	0	0	0		
PCB板	Х	0	0	0	0	0		
电气连接 器	0	0	0	0	0	0		
压电晶 体	Х	0	0	0	0	0		
环氧	0	0	0	0	0	0		
铁氟龙	0	0	0	0	0	0		
电子	0	0	0	0	0	0		
厚膜基板	0	0	Х	0	0	0		
电线	0	0	0	0	0	0		
电缆	х	0	0	0	0	0		
塑料	0	0	0	0	0	0		
焊接	Х	0	0	0	0	0		
铜合金 /黄 铜	Х	0	0	0	0	0		
本表格依据 SJ/T 11364 的规定编制。								
O:表示该有害物质在该部件所有均质材料中的含量均在 GB/T 26572 规定的限量要求以下。								
X:表示该有害物质至少在该部件的某一均质材料中的含量超出 GB/T 26572 规定的限量要求。								
铅是欧洲RoHS指名	令2011/65/ E	J附件三	和附件四	目前由于允 许的豁	免。			

CHINA ROHS COMPLIANCE

Hazardous Substances								
Lead (Pb)	Mercury (Hg)	Cadmium (Cd)	Chromium VI Compounds (Cr(VI))	Polybrominated Biphenyls (PBB)	Polybrominated Diphenyl Ethers (PBDE)			
0	0	0	0	0	0			
Х	0	0	0	0	0			
0	0	0	0	0	0			
Х	0	0	0	0	0			
0	0	0	0	0	0			
0	0	0	0	0	0			
0	0	0	0	0	0			
0	0	Х	0	0	0			
0	0	0	0	0	0			
Х	0	0	0	0	0			
0	0	0	0	0	0			
Х	0	0	0	0	0			
Х	0	0	0	0	0			
	Lead (Pb)	Lead (Pb) Mercury (Hg) 0 0 0 0 X 0 0 0 X 0 0 0 X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 X 0 X 0 X 0 X 0	Lead (Pb) Mercury (Hg) Cadmium (Cd) 0 0 0 0 0 0 X 0 0 X 0 0 X 0 0 X 0 0 0 0 0 X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 X 0 0 X 0 0 X 0 0	Hazerdous SubstancesLead (Pb)Mercury (Hg)Cadmium (Cd)Chromium VI Compounds (r(VI))000000001000010000100001000010000100001000010000100100100100100001000010000100001100012000130001400015000	Hazardous ConstructionHarcury (Hg)Cadmium (Cd)Chromium VI Compounds (Cr(VI))Polybrominated Biphenyls (PBB) (Cr(VI))000000000010			

This table is prepared in accordance with the provisions of SJ/T 11364.

O: Indicates that said hazardous substance contained in all of the homogeneous materials for this part is below the limit requirement of GB/T 26572.

X: Indicates that said hazardous substance contained in at least one of the homogeneous materials for this part is above the limit requirement of GB/T 26572.

Lead is present due to allowed exemption in Annex III or Annex IV of the European RoHS Directive 2011/65/EU.

Model Number					Revision: E
352B10		ICP® ACCELE		DMETER	ECN #: 42197
Performance	ENGLISH	SI			I
Sensitivity(+ 10 %)	10 mV/g	1.02 mV/(m/s^2)		Ontional versions have identical specifications and accessories as	listed for the standard model
Measurement Range	+ 500 g pk	+ 4905 m/s ² nk		excent where noted below. More than one option n	hav be used
Frequency Range(+ 5 %)	2 to 10 000 Hz	2 to 10 000 Hz			
Frequency Range(± 10 %)	1 to 17,000 Hz	1 to 17 000 Hz		HT - High temperature, extends normal operation temperatures	
Posoport Fraguency	> 65 kHz	> 65 447		Tomporature Pange(Operating) 65 to 325 °E	54 to 163 °C
Resolution (1 to 10 000 Hz)	2 03 KHZ 0.003 g rms	200 KHZ	[1]	Temperature Range(Operating) -05 to 525 P	-54 10 165 C
Non Linearity	0.003 g mis	0.03 11/5-1115	[1]	W. Water Registent Cable	
Transverse Canaitivity	≤ % < 5 %	≤ 1 % < 5 0/	[3]		00 / 404 00
	≤ 5 %	≤ 5 %		Temperature Range(Operating) -20 to 220 °F	-29 to 104 °C
	10,000			Electrical Connector Sealed Integral Cable	Sealed Integral Cable
Overload Limit(Shock)	± 10,000 g pk	± 98,100 m/s² pk	[0]	Cable Type 018 Coaxial	018 Coaxial
Temperature Range(Operating)	-65 to +250 °F	-54 to +121 °C	[2]		
Temperature Response	See Graph	See Graph			
Electrical					
Excitation Voltage	18 to 30 VDC	18 to 30 VDC			
Constant Current Excitation	2 to 20 mA	2 to 20 mA			
Output Impedance	≤ 200 Ohm	≤ 200 Ohm			
Output Bias Voltage	7 to 12 VDC	7 to 12 VDC			
Discharge Time Constant	0.3 to 1.0 sec	0.3 to 1.0 sec			
Settling Time(within 10% of bias)	<3 sec	<3 sec			
Spectral Noise(1 Hz)	1000 µg/√Hz	9810 (µm/sec ²)/√Hz	[1]		
Spectral Noise(10 Hz)	300 µg/√Hz	2943 (um/sec ²)/√Hz	[1]	NOTES:	
Spectral Noise(100 Hz)	80 µg/√Hz	785 (µm/sec ²)/√Hz	[1]	[1] Typical.	
Spectral Noise(1 kHz)	25 µg/√Hz	$308 (\mu m/soc^2)/3/Hz$	[1]	[2] 250° F to 325° F data valid with HT option only.	
Physical	20 µg/ 112	508 (µ11/sec)/ 112	1.1	[3] Zero-based, least-squares, straight line method.	
Cize (Diameter y Lleight)	0.04 in x 0.00 in	6.1 mm x 8.1 mm		[4] See PCB Declaration of Conformance PS023 for details.	
	0.24 III X 0.32 III	0.1 mm x 8.1 mm	[4]		
overgrit	0.03.02	0.7 gm	[1]		
	Ceramic	Ceramic			
Sensing Geometry	Snear	Shear			
Housing Material	litanium	litanium			
Sealing	Hermetic	Hermetic			
Electrical Connector	Solder pins with attached cable	Solder pins with attached cable	•		
Electrical Connection Position	Тор	Тор			
Cable Termination	10-32 Coaxial Plug	10-32 Coaxial Plug			
Cable Length	10 ft	3 m			
Cable Type	030 Coaxial	030 Coaxial			
Mounting	Adhesive	Adhesive			
	Typical Sensitiv	ity Deviation vs Temperature		SUPPLIED ACCESSORIES: Model 080A109 Petro Wax (1) Model 080A90 Quick Bonding Gel (1) Model 04CS-1 NIST traceable frequency response (10 Hz to upper 6	5% point) (1)
	> 10 <u> </u>			model need in mor traceable nequency response (10 Hz to upper a	
	ie -10		•		
[4]	. <u></u>				
	ຮູ -100-50 U	50 100 150 200 250 300	350	Entered: AP Engineer: JJB Sales: WDC Approved	a: JJB Spec Number:
		Temperature (°F)		Date: 11/8/2013 Date: 11/8/2013 Date: 11/8/2013 Date: 11/8/2013	/8/2013 15312
All specifications are at room temperatu In the interest of constant product impro ICP [®] is a registered trademark of PCB (re unless otherwise specified. vement, we reserve the right to chang Group, Inc.	ge specifications without notice.		PCB PIEZOTRONICS ^{**}	hone: 716-684-0001 ax: 716-684-0987 Mail: info@pcb.com



Model 086C04

Modally Tuned® Impulse Hammer w/force sensor and tips, 0 to 1k lbf, 5 mV/lbf (1.1 mV/N)

Installation and Operating Manual

For assistance with the operation of this product, contact the PCB Piezotronics, Inc.

Toll-free: 716-684-0001 24-hour SensorLine: 716-684-0001 Fax: 716-684-0987 E-mail: info@pcb.com Web: www.pcb.com







Repair and Maintenance

PCB guarantees Total Customer Satisfaction through its "Lifetime Warranty Plus" on all Platinum Stock Products sold by PCB and through its limited warranties on all other PCB Stock, Standard and Special products. Due to the sophisticated nature of our sensors and associated instrumentation, field servicing and repair is not recommended and, if attempted, will void the factory warranty.

Beyond routine calibration and battery replacements where applicable, our products require no user maintenance. Clean electrical connectors, housings, and mounting surfaces with solutions and techniques that will not harm the material of construction. Observe caution when using liquids near devices that are not hermetically sealed. Such devices should only be wiped with a dampened cloth—never saturated or submerged.

In the event that equipment becomes damaged or ceases to operate, our Application Engineers are here to support your troubleshooting efforts 24 hours a day, 7 days a week. Call or email with model and serial number as well as a brief description of the problem.

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	有害物 质								
部件名称	铅 (Pb)	汞 (Hg)	镉 (Cd)	六价铬 (Cr(VI))	多溴 联苯 (PBB)	多溴二苯 醚 (PBDE)			
住房	0	0	0	0	0	0			
PCB板	Х	0	0	0	0	0			
电气连接 器	0	0	0	0	0	0			
压电晶 体	Х	0	0	0	0	0			
环氧	0	0	0	0	0	0			
铁氟龙	0	0	0	0	0	0			
电子	0	0	0	0	0	0			
厚膜基板	0	0	Х	0	0	0			
电线	0	0	0	0	0	0			
电缆	х	0	0	0	0	0			
塑料	0	0	0	0	0	0			
焊接	Х	0	0	0	0	0			
铜合金 /黄 铜	Х	0	0	0	0	0			
本表格依据 SJ/T 1	. 1364 的 规定	编制。							
O:表示该有害物质在该部件所有均质材料中的含量均在 GB/T 26572 规定的限量要求以下。									
X:表示该有害物	质至少在该	部件的某	一均质相	才料中的含量超出 (求。			
铅是欧洲RoHS指名	令2011/65/ E	∪附件三ः	和附件匹	目前由于允 许的豁	免。				

Hazardous Substances									
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0	0	0	0	0	0				
Х	0	0	0	0	0				
0	0	0	0	0	0				
Х	0	0	0	0	0				
0	0	0	0	0	0				
0	0	0	0	0	0				
0	0	0	0	0	0				
0	0	Х	0	0	0				
0	0	0	0	0	0				
Х	0	0	0	0	0				
0	0	0	0	0	0				
Х	0	0	0	0	0				
Х	0	0	0	0	0				
	Lead (Pb)	Lead (Pb) Mercury (Hg) 0 0 0 0 X 0 0 0 X 0 0 0 X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 X 0 X 0 X 0	Lead (Pb) Mercury (Hg) Cadmium (Cd) 0 0 0 0 0 0 X 0 0 X 0 0 X 0 0 X 0 0 X 0 0 X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 X 0 0 X 0 0 X 0 0	Hazerdous SubstancesLead (Pb)Mercury (Hg)Cadmium (Cd)Chromium VI Compounds (r(VI))000000001000010000100001000010000100001000010000100100100100100001000010000100001100012000130001400015000	Hazardous ConstructionHarcury (Hg)Cadmium (Cd)Chromium VI Compounds (Cr(VI))Polybrominated Biphenyls (PBB) (Cr(VI))000000000010				

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Model Number 086C04		ICP® IMPACT HAMMER						
Performance Sensitivity(± 15 %) Measurement Range Resonant Frequency Non-Linearity Electrical Exciticing Voltage	ENGLISH 5 mV/lbf ± 1000 lbf pk ≥ 22 kHz ≤ 1 %	<u>SI</u> 1.1 mV/N ± 4448 N pk ≥ 22 kHz ≤ 1 %		OPTIONAL VERSIONS Optional versions have identical specifications and accessories as listed for the standard model except where noted below. More than one option may be used. TLD - TEDS Capable of Digital Memory and Communication Compliant with IEEE 1451.4				
Constant Current Excitation Output Impedance Output Bias Voltage Discharge Time Constant	2 to 20 mA <100 Ohm 8 to 14 VDC ≥ 2000 sec	2 to 20 mA <100 Ohm 8 to 14 VDC ≥ 2000 sec	[1] [1]	NOTES: [1] Typical. [2] See PCB De	claration of Conforn	nance PS068 for de	tails.	
Physical Sensing Element Sealing Hammer Mass Head Diameter Tip Diameter Hammer Length Electrical Connection Positio Extender Mass Weight Electrical Connector	Quartz Epoxy 0.34 lb 0.62 in 0.25 in 8.5 in on Bottom of Handle 2.6 oz BNC Jack	Quartz Epoxy 0.16 kg 1.57 cm 0.63 cm 21.6 cm Bottom of Handle 75 gm BNC Jack		SUPPLIED ACCESSORIES: Model 081B05 Mounting Stud (10-32 to 10-32) (2) Model 084A08 Extender - Steel, 0.6" Diameter (1) Model 084B03 Hard Tip- Hard (S.S) (1) Model 084B04 Hammer Tip- Medium (White Plastic) (1) Model 084C05 Hammer Tip- Soft (Black) (2) Model 084C11 Hammer Tip- Supersoft (Red) (2) Model 085A10 Vinyl Cover For Medium Tip (Blue) (2) Model HCS-2 Calibration of Series 086 instrumented impact hammers (1)				
				Entered: LK	Engineer: KW	Sales: AT	Approved: BAM	Spec Number:
All specifications are at room In the interest of constant pr ICP [®] is a registered tradema	n temperature unless otherwise specified. roduct improvement, we reserve the right to chang ark of PCB Group, Inc.	e specifications without notice	ð.	Date: 8/9/2018	Date: 8/9/2018	Date: 8/9/2018	Date: 8/9/2018 Phone: ⁻ Fax: 716 E-Mail: i	15274 716-684-0001 5-684-0987 nfo@pcb.com



Model 480E09

Short sledge Impact Hammer kit, 0 to 5k lbf, 1 mV/lbf, 2.4-lb head, with 2 ea.

Installation and Operating Manual

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Toll-free: 800-828-8840 24-hour SensorLine: 716-684-0001 Fax: 716-684-0987 E-mail: info@pcb.com Web: www.pcb.com







PCB guarantees Total Customer Satisfaction through its "Lifetime Warranty Plus" on all Platinum Stock Products sold by PCB and through its limited warranties on all other PCB Stock, Standard and Special products. Due to the sophisticated nature of our sensors and associated instrumentation, field servicing and repair is not recommended and, if attempted, will void the factory warranty.

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PCB板	Х	0	0	0	0	0			
电气连接 器	0	0	0	0	0	0			
压电晶 体	Х	0	0	0	0	0			
环氧	0	0	0	0	0	0			
铁氟龙	0	0	0	0	0	0			
电子	0	0	0	0	0	0			
厚膜基板	0	0	Х	0	0	0			
电线	0	0	0	0	0	0			
电缆	х	0	0	0	0	0			
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铅是欧洲RoHS指名	令2011/65/ E	∪附件三ः	和附件匹	目前由于允 许的豁	免。				

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0	0	0	0	0	0				
Х	0	0	0	0	0				
0	0	0	0	0	0				
Х	0	0	0	0	0				
0	0	0	0	0	0				
0	0	0	0	0	0				
0	0	0	0	0	0				
0	0	Х	0	0	0				
0	0	0	0	0	0				
Х	0	0	0	0	0				
0	0	0	0	0	0				
Х	0	0	0	0	0				
Х	0	0	0	0	0				
	Lead (Pb)	Lead (Pb) Mercury (Hg) 0 0 0 0 X 0 0 0 X 0 0 0 X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 X 0 X 0 X 0	Lead (Pb) Mercury (Hg) Cadmium (Cd) 0 0 0 0 0 0 X 0 0 X 0 0 X 0 0 X 0 0 X 0 0 X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 X 0 0 X 0 0 X 0 0	Hazerdous SubstancesLead (Pb)Mercury (Hg)Cadmium (Cd)Chromium VI Compounds (r(VI))000000001000010000100001000010000100001000010000100100100100100001000010000100001100012000130001400015000	Hazardous ConstructionHarcury (Hg)Cadmium (Cd)Chromium VI Compounds (Cr(VI))Polybrominated Biphenyls (PBB) (Cr(VI))000000000010				

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Model Number 480E09	BATTERY-POWERED SIGNAL CONDITIONER Revision: V ECN #: 45339								
Performance		ENGLISH	SI		1	OP	TIONAL VERSI	ONS	
Channels		1	1		Optional version	ons have identical	specifications and ac	cessories as listed f	or the standard
Frequency Range(-5 %)	(x1, x10 Gain)	0.15 to 100,000 Hz	0.15 to 100,000 Hz	[6]	mode	el except where not	ed below. More than	one option may be	used.
Frequency Range(-10 % Voltage Gain(± 2 %))(x100 Gain)	0.15 to 50,000 Hz 1:1	0.15 to 50,000 Hz 1:1	[7]					
Voltage Gain(± 2 %)		1:10	1:10						
Voltage Gain(± 2 %)		1:100	1:100						
Fault/Bias Monitor/Meter	(± 1 V)(midscale)	13 VDC	13 VDC						
Environmental									
Temperature Range		32 to 120 °F	0 to 50 °C						
Electrical									
Excitation Voltage(To Se	ensor)	25 to 29 VDC	25 to 29 VDC	[1]					
Constant Current Excitat	ion(To Sensor)	2.0 to 3.2 mA	2.0 to 3.2 mA	[2]					
Discharge Time Constan	nt	>7 sec	>7 sec	[3][4]					
DC Offset(Maximum)		<30 mV	<30 mV	[3]					
Spectral Noise(1 Hz)(Ga	in 1)	.25 µV/√Hz	-132 dB						
Spectral Noise(10 Hz)(G	ain 1)	.07 µV/√Hz	-143 dB						
Spectral Noise(100 Hz)(Gain 1)	.05 µV/√Hz	-146 dB		NOTES				
Spectral Noise(1 kHz)(G	ain 1)	.04 µV/√Hz	-148 dB		[1]Excitation volta	ine to sensor limiter	hy optional DC pow	ver voltage	
Spectral Noise(10 kHz)(Gain 1)	.03 µV/√Hz	-150 dB		[1]Excitation volta	al current limiting re	a by optional DC pov	ver vollage.	
Broadband Electrical No	ise(1 to 10,000 Hz)(Gain x1)	3.25 µV rms	-110 dB/rms		[3]With 1M ohm lo	pad.	gulator.		
Spectral Noise(1 Hz)(Ga	in 10)	2.2 µV/√Hz	-113 dB		[4]Un-buffered ou	tput, read out devic	e input impedance a	affects discharge time	e constant and low
Spectral Noise(10 Hz)(G	ain 10)	2.0 µV/√Hz	-114 dB		frequency resp	onse of unit.			
Spectral Noise(100 Hz)(Gain 10)	1.1 µV/√Hz	-119 dB		[5]Provided by op	tional external DC	power supply.		
Spectral Noise(1 kHz)(G	ain 10)	.55 µV/√Hz	-125 dB		[6]Low frequency	response specified	into 1M ohm load.		
Spectral Noise(10 kHz)(Gain 10)	.3 µV/√Hz	-130 dB		[7]After Serial Nu	mber 24699, previo	usly HFR was 100kh	Hz.	
Broadband Electrical No	ise(1 to 10,000 Hz)(Gain x10)	49 µV/rms	-86 dB/rms		[8]See PCB Decia	aration of Conforma	ince PS024 for detai	IS.	
Spectral Noise(1 Hz)(Ga	in 100)	20 µV/√Hz	-94 dB						
Spectral Noise(10 Hz)(G	ain 100)	19 µV/√Hz	-94 dB						
Spectral Noise(100 Hz)(Gain 100)	12 µV/√Hz	-98 dB						
Spectral Noise(1 kHz)(G	ain 100)	5.5 µV/√Hz	-105 dB						
Spectral Noise(10 kHz)(Gain 100)	2 µV/√Hz	-114 dB						
Broadband Electrical No	ise(1 to 10,000 Hz)(Gain x100)	569 μV/rms	-65 dB/rms						
Power Required(Standar	rd)	Internal Battery	Internal Battery						
Internal Battery(Type)		9V	9V						
Battery Life(Standard All	(aline)	50 hours	50 hours						
Power Required(Alternat	te)	DC power	DC power						
DC Power		15 mA	15 mA	[5]					
Internal Battery(Quantity)	3	3						
DC Power		18 to 30 VDC	18 to 30 VDC	[5][1]					
Physical									
Electrical Connector(Inpu	ut, sensor)	BNC Jack	BNC Jack						
Electrical Connector(Out	put, scope)	BNC Jack	BNC Jack						
Electrical Connector(Exte	ernal Power, DC)	3.5 mm Diameter Miniature Jack	3.5 mm Diameter Miniature Jack	9					
Electrical Connector(Bat	tery Charger)	#722 Switchcraft Jack	#722 Switchcraft Jack						
Size (Depth x Height x W	/idth)	2.4 in x 4.0 in x 2.9 in	6.1 cm x 10 cm x 7.4 cm			-			
Weight(Including Batterie	es)	0.7 lb	0.3 kg		Entered: LK	Engineer: CPH	Sales: ML	Approved: JWH	Spec Number:
					Date: 5/22/2016	Data: 5/22/2016	Date: 5/22/2016	Dete: 5/22/2016	400 5000 00
					Date. 5/23/2016	Date. 3/23/2016	Date. 5/25/2016	Date. 3/23/2016	480-5090-80
[8]									
All specifications are at n	nom temperature unless other	wise specified			Anco			Phone: 71	6-684-0001
In the interest of constant	t product improvement, we res	erve the right to change so	ecifications without notice		TLE	MEZUIN	UNILS	Fax: 716-6	84-0987
ICP [®] is a registered trade	emark of PCB Group. Inc.	5			3425 Walden Ave	nue, Depew, NY 14	043	E-Mail: inf	o@pcb.com
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PCB板	Х	0	0	0	0	0			
电气连接 器	0	0	0	0	0	0			
压电晶 体	Х	0	0	0	0	0			
环氧	0	0	0	0	0	0			
铁氟龙	0	0	0	0	0	0			
电子	0	0	0	0	0	0			
厚膜基板	0	0	Х	0	0	0			
电线	0	0	0	0	0	0			
电缆	х	0	0	0	0	0			
塑料	0	0	0	0	0	0			
焊接	Х	0	0	0	0	0			
铜合金 /黄 铜	Х	0	0	0	0	0			
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铅是欧洲RoHS指名	令2011/65/ E	∪附件三ः	和附件匹	目前由于允 许的豁	免。				

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0	0	0	0	0	0				
Х	0	0	0	0	0				
0	0	0	0	0	0				
Х	0	0	0	0	0				
0	0	0	0	0	0				
0	0	0	0	0	0				
0	0	0	0	0	0				
0	0	Х	0	0	0				
0	0	0	0	0	0				
Х	0	0	0	0	0				
0	0	0	0	0	0				
Х	0	0	0	0	0				
Х	0	0	0	0	0				
	Lead (Pb)	Lead (Pb) Mercury (Hg) 0 0 0 0 X 0 0 0 X 0 0 0 X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 X 0 X 0 X 0	Lead (Pb) Mercury (Hg) Cadmium (Cd) 0 0 0 0 0 0 X 0 0 X 0 0 X 0 0 X 0 0 X 0 0 X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 X 0 0 X 0 0 X 0 0	Hazerdous SubstancesLead (Pb)Mercury (Hg)Cadmium (Cd)Chromium VI Compounds (r(VI))000000001000010000100001000010000100001000010000100100100100100001000010000100001100012000130001400015000	Hazardous ConstructionHarcury (Hg)Cadmium (Cd)Chromium VI Compounds (Cr(VI))Polybrominated Biphenyls (PBB) (Cr(VI))000000000010				

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	1								
	REVISIONS								
REV	DESCRIPTION	DIN							
NR	RELEASED TO DRAFTING	50133							
-									





Model 086C04

Modally Tuned® Impulse Hammer w/force sensor and tips, 0 to 1k lbf, 5 mV/lbf (1.1 mV/N)

Installation and Operating Manual

For assistance with the operation of this product, contact the PCB Piezotronics, Inc.

Toll-free: 716-684-0001 24-hour SensorLine: 716-684-0001 Fax: 716-684-0987 E-mail: info@pcb.com Web: www.pcb.com







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环氧	0	0	0	0	0	0			
铁氟龙	0	0	0	0	0	0			
电子	0	0	0	0	0	0			
厚膜基板	0	0	Х	0	0	0			
电线	0	0	0	0	0	0			
电缆	х	0	0	0	0	0			
塑料	0	0	0	0	0	0			
焊接	Х	0	0	0	0	0			
铜合金 /黄 铜	Х	0	0	0	0	0			
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O:表示该有害物质在该部件所有均质材料中的含量均在 GB/T 26572 规定的限量要求以下。									
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Х	0	0	0	0	0				
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0	0	0	0	0	0				
0	0	0	0	0	0				
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0	0	0	0	0	0				
Х	0	0	0	0	0				
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0	0	0	0	0	0	
Х	0	0	0	0	0	
0	0	0	0	0	0	
0	0	0	0	0	0	
0	0	0	0	0	0	
0	0	Х	0	0	0	
0	0	0	0	0	0	
Х	0	0	0	0	0	
0	0	0	0	0	0	
Х	0	0	0	0	0	
Х	0	0	0	0	0	
	Lead (Pb)	Lead (Pb) Mercury (Hg) 0 0 0 0 X 0 0 0 X 0 0 0 X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 X 0 X 0 X 0 X 0	Lead (Pb) Mercury (Hg) Cadmium (Cd) 0 0 0 0 0 0 X 0 0 X 0 0 X 0 0 X 0 0 0 0 0 X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 X 0 0 X 0 0 X 0 0	Hazerdous SubstancesLead (Pb)Mercury (Hg)Cadmium (Cd)Chromium VI Compounds (r(VI))000000001000010000100001000010000100001000010000100100100100100001000010000100001100012000130001400015000	Hazardous ConstructionHarcury (Hg)Cadmium (Cd)Chromium VI Compounds (Cr(VI))Polybrominated Biphenyls (PBB) (Cr(VI))000000000010	

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REVISIONS							
REV	DESCRIPTION	DIN					
NR	RELEASED TO DRAFTING	50133					

	CHECKED		ENGINEER					
20	JES	1/3/20	ВАМ	1/3/20				
DUTLINE DRAWING ERIES & 003EBXXXAC SERIES AL CABLE W/ 10-32 & BNC					(716) 684-0001 E-MAIL: sales@pcb.com			
					CODE IDENT. NO. 52681	DWG. NO.	7252	26
	PLU	GS			SCALE:	2.5X	SHEET	1 OF 1

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Model 352C68

ACCELEROMETER KIT

Installation and Operating Manual

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The following symbols may be used in this manual:



DANGER



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PCB板	Х	0	0	0	0	0		
电气连接 器	0	0	0	0	0	0		
压电晶 体	Х	0	0	0	0	0		
环氧	0	0	0	0	0	0		
铁氟龙	0	0	0	0	0	0		
电子	0	0	0	0	0	0		
厚膜基板	0	0	Х	0	0	0		
电线	0	0	0	0	0	0		
电缆	电缆 X O							
塑料	0	0	0	0	0	0		
焊接	Х	0	0	0	0	0		
铜合金 /黄 铜	Х	0	0	0	0	0		
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0	0	0	0	0	0	
Х	0	0	0	0	0	
0	0	0	0	0	0	
Х	0	0	0	0	0	
0	0	0	0	0	0	
0	0	0	0	0	0	
0	0	0	0	0	0	
0	0	Х	0	0	0	
0	0	0	0	0	0	
Х	0	0	0	0	0	
0	0	0	0	0	0	
Х	0	0	0	0	0	
Х	0	0	0	0	0	
	Lead (Pb)	Lead (Pb) Mercury (Hg) 0 0 0 0 X 0 0 0 X 0 0 0 X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 X 0 X 0 X 0 X 0	Lead (Pb) Mercury (Hg) Cadmium (Cd) 0 0 0 0 0 0 X 0 0 X 0 0 X 0 0 X 0 0 0 0 0 X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 X 0 0 X 0 0 X 0 0	Hazerdous SubstancesLead (Pb)Mercury (Hg)Cadmium (Cd)Chromium VI Compounds (r(VI))000000001000010000100001000010000100001000010000100100100100100001000010000100001100012000130001400015000	Hazardous ConstructionHarcury (Hg)Cadmium (Cd)Chromium VI Compounds (Cr(VI))Polybrominated Biphenyls (PBB) (Cr(VI))000000000010	

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Model 352B10

Miniature, lightweight (0.7 gm), ceramic shear ICP® accel., 10 mV/g, 2 to

Installation and Operating Manual

For assistance with the operation of this product, contact PCB Piezotronics, Inc.

Toll-free: 800-828-8840 24-hour SensorLine: 716-684-0001 Fax: 716-684-0987 E-mail: info@pcb.com Web: www.pcb.com







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压电晶 体	Х	0	0	0	0	0		
环氧	0	0	0	0	0	0		
铁氟龙	0	0	0	0	0	0		
电子	0	0	0	0	0	0		
厚膜基板	0	0	Х	0	0	0		
电线	0	0	0	0	0	0		
电缆	х	0	0	0	0	0		
塑料	0	0	0	0	0	0		
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CHINA ROHS COMPLIANCE

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0	0	0	0	0	0		
Х	0	0	0	0	0		
0	0	0	0	0	0		
Х	0	0	0	0	0		
0	0	0	0	0	0		
0	0	0	0	0	0		
0	0	0	0	0	0		
0	0	Х	0	0	0		
0	0	0	0	0	0		
Х	0	0	0	0	0		
0	0	0	0	0	0		
Х	0	0	0	0	0		
Х	0	0	0	0	0		
	Lead (Pb)	Lead (Pb) Mercury (Hg) 0 0 0 0 X 0 0 0 X 0 0 0 X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 X 0 X 0 X 0 X 0	Lead (Pb) Mercury (Hg) Cadmium (Cd) 0 0 0 0 0 0 10 0 0	Hazerdous SubstancesLead (Pb)Mercury (Hg)Cadmium (Cd)Chromium VI Compounds (r(VI))000000001000010000100001000010000100001000010000100100100100100001000010000100001100012000130001400015000	Hazardous ConstructionHarcury (Hg)Cadmium (Cd)Chromium VI Compounds (Cr(VI))Polybrominated Biphenyls (PBB) (Cr(VI))000000000010		

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CHINA ROHS COMPLIANCE

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Х	0	0	0	0	0		
0	0	0	0	0	0		
Х	0	0	0	0	0		
0	0	0	0	0	0		
0	0	0	0	0	0		
0	0	0	0	0	0		
0	0	Х	0	0	0		
0	0	0	0	0	0		
Х	0	0	0	0	0		
0	0	0	0	0	0		
Х	0	0	0	0	0		
Х	0	0	0	0	0		
	Lead (Pb)	Lead (Pb) Mercury (Hg) 0 0 0 0 X 0 0 0 X 0 0 0 X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 X 0 X 0 X 0 X 0	Lead (Pb) Mercury (Hg) Cadmium (Cd) 0 0 0 0 0 0 10 0 0	Hazerdous SubstancesLead (Pb)Mercury (Hg)Cadmium (Cd)Chromium VI Compounds (r(VI))000000001000010000100001000010000100001000010000100100100100100001000010000100001100012000130001400015000	Hazardous ConstructionHarcury (Hg)Cadmium (Cd)Chromium VI Compounds (Cr(VI))Polybrominated Biphenyls (PBB) (Cr(VI))000000000010		

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	1	
	REVISIONS	
REV	DESCRIPTION	DIN
NR	RELEASED TO DRAFTING	50133
-		





Model GK291D04

Modally Tuned® Impact Hammer kit, 0 to 1k lbf, 5 mV/lbf, Contents included... (1) 086C04, (1) 352C68, (1) 352B10, (2) 480E09, (2) 003D03, (2) 003C10, (1) 003D10, (1) 070A02, (1) 001A11, Outline 5051

Installation and Operating Manual

This manual contains the 003C10, 003D03, 003D10, 086C04, 352B10, 352C68, 480E09 installation and operating manuals that comprise a Model GK291D04 Modally Tuned® Impact Hammer kit, 0 to 1k lbf, 5 mV/lbf, Contents included... (1) 086C04, (1) 352C68, (1) 352B10, (2) 480E09, (2) 003D03, (2) 003C10, (1) 003D10, (1) 070A02, (1) 001A11, Outline 5051 kit.

For assistance with the operation of this product, contact the PCB Piezotronics, Inc.

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电子	0	0	0	0	0	0		
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0	0	0	0	0	0		
Х	0	0	0	0	0		
0	0	0	0	0	0		
Х	0	0	0	0	0		
0	0	0	0	0	0		
0	0	0	0	0	0		
0	0	0	0	0	0		
0	0	Х	0	0	0		
0	0	0	0	0	0		
Х	0	0	0	0	0		
0	0	0	0	0	0		
Х	0	0	0	0	0		
Х	0	0	0	0	0		
	Lead (Pb)	Lead (Pb) Mercury (Hg) 0 0 0 0 X 0 0 0 X 0 0 0 X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 X 0 X 0 X 0 X 0	Lead (Pb) Mercury (Hg) Cadmium (Cd) 0 0 0 0 0 0 10 0 0	Hazerdous SubstancesLead (Pb)Mercury (Hg)Cadmium (Cd)Chromium VI Compounds (r(VI))000000001000010000100001000010000100001000010000100100100100100001000010000100001100012000130001400015000	Hazardous ConstructionHarcury (Hg)Cadmium (Cd)Chromium VI Compounds (Cr(VI))Polybrominated Biphenyls (PBB) (Cr(VI))000000000010		

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